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## Using Compiler Techniques to Improve Automatic Performance Modeling

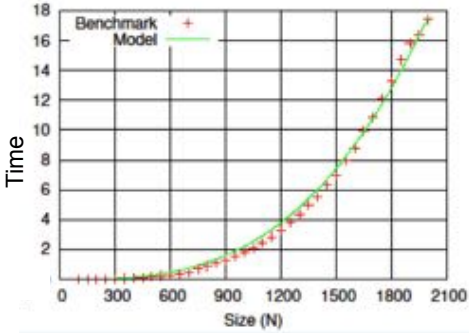
ARNAMOY BHATTACHARYYA, GRZEGORZ KWASNIEWSKI, TORSTEN HOEFLER



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## AUTOMATING PERFORMANCE MODEL GENERATION

- Representing performance as function of program inputs
  - $T(N) = tN^3$
  - POWER7
  - $t=2.2ns^1$



1. T. Hoefler, W. Gropp, M. Snir and W. Kramer: Performance Modeling for Systematic Performance Tuning In *International Conference for High Performance Computing, Networking, Storage and Analysis (SC'11)*, SoP Session, Nov. 2011

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## AUTOMATING PERFORMANCE MODEL GENERATION

### Why?

1. Scalability
2. Insight into requirements

We want to generate models **ON THE FLY**

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## AUTOMATING PERFORMANCE MODEL GENERATION

- Existing techniques:
  - Static: Counts Loop iterations
  - Dynamic: Use ML on profiled data

### Problems:

Static Analysis [SPAA '14]: *Imprecise* sometimes

Dynamic Analysis [PACT '14]: *Overhead* restrictions


When **ON THE FLY**, overhead should be negligible

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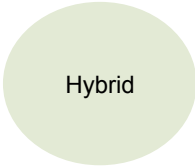
## AUTOMATING PERFORMANCE MODEL GENERATION

Best of both worlds



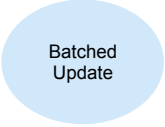
Static



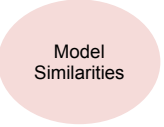


Hybrid

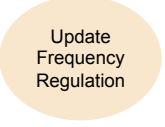
Precision – Upto **10% improvement** (on avg. 4.5%)



Batched Update



Model Similarities



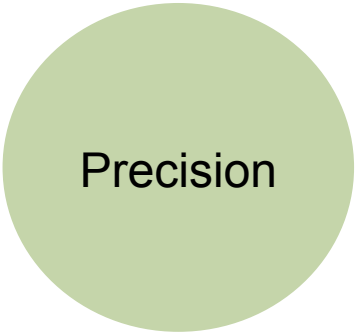
Update Frequency Regulation

Overhead – Upto **65% reduction** (on average 25%)


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## Our technique





Precision



Overhead

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## Dynamic Analysis

- **Main Idea:**
- **Generating a model by “selecting” the best features from a bag of “candidate features”**

$$p = \{\iota_i^k \log^l \iota_i^k, k, l \in \mathbb{R}, \iota_i \in I\}$$

- **Example:**
- Program input:  $n$
- We select  $k=\{1,2\}$  and  $l = \{0,1\}$
- Bag of features =  $n, n^2, n \log n, n^2 \log n^2$
- ON THE FLY feature selection

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## Dynamic Analysis

- **Main Idea:**
- **Generating a model by “selecting” the best features from a bag of “candidate features”**

$$p = \{\iota_i^k \log^l \iota_i^k, k, l \in \mathbb{R}, \iota_i \in I\}$$

- **Example with two inputs:**
- Program input:  $n, m$
- We select  $k=\{1,2\}$  and  $l = \{0,1\}$
- Bag of features =  $n, n^2, n \log n, n^2 \log n^2, m, m^2, m \log m, m^2 \log m^2$
- BUT... What about terms like  $n \cdot m$  or  $n m^3 \log m^2$ ??

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## Static Analysis

Count # of iterations as a function of program inputs

- Existing methods –
  - i) Polyhedral Model
  - ii) Hoefler – Kwasnewski method [SPAA '14]

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## Static Analysis

- Hoefler –Kwasnewski method [SPAA '14]

**“Better” than polyhedral!**



- i) Over approximation (e.g `iter_variable = iter_variable *2`)
- ii) No support for non-constant updates

```

j=1;
k=5;
while (j>0){
  j=j+k;
  k--;
}

```

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## Static Analysis

### Problem:

- Still can't handle some specific loops (e.g. indirection in loop condition)
 

```
do j=1, lastrow-firstrow+1 sum = 0.d0
  do k=rowstr(j), rowstr(j+1)-1
    sum = sum + a(k)*p(colidx(k))
  enddo
  w(j) = sum
enddo
```
- Give *undef* terms in the model
 
$$\# \text{ iterations} = (\text{lastrow} - \text{firstrow}) * \text{undef}$$

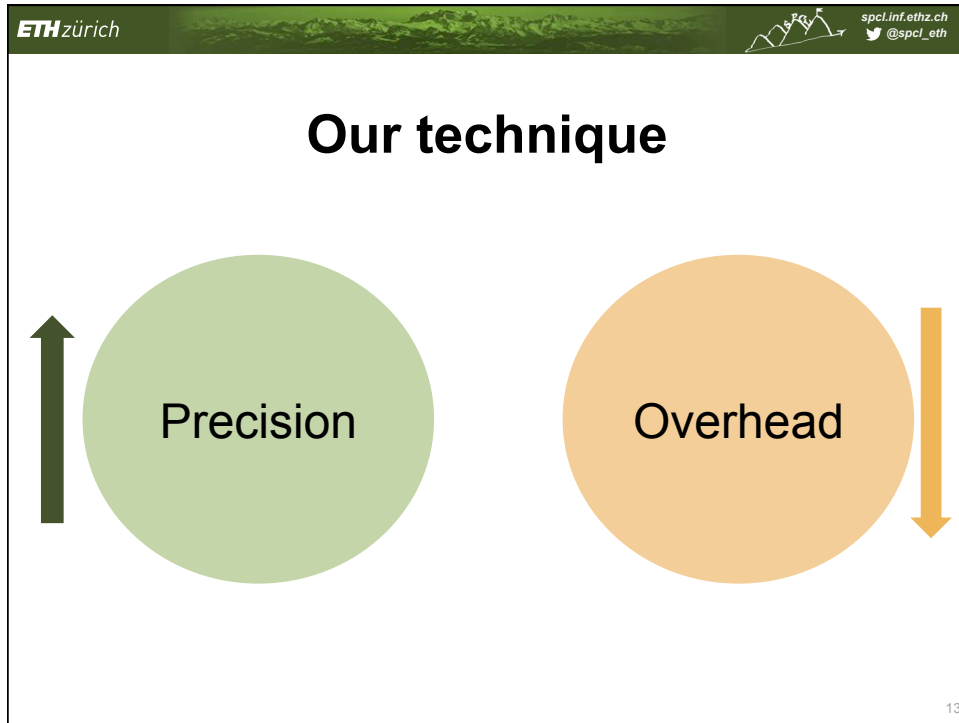
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## Our Contribution: Combining two

- Extract predictors (even *interaction terms* 😊) from the static model
- If *undef*, use profiling and ML dynamically.
- Include interaction terms in bag of features.

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### Overhead reduction:

1. Batched model update
  - ON THE FLY modeling
  - Function call overhead



```

if (cell_coord(1,c) .ne. ncells) then
  do k = 0, cell_size(3,c)-1
    do j = 0, cell_size(2,c)-1
      do i = cell_size(1,c)-2, cell_size(1,c)-1
        do m = 1, 5
          out_buffer(ss(0)+p0) = u(m,i,j,k,c)
          p0 = p0 + 1
        end do
      end do
    end do
  end do
end do

```

6 million iterations, for 16 processes  
1.6% overhead just from this loop  
23% in total

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## Overhead reduction:

### 1. Batched model update

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```



if (cell_coord(1,c) .ne. ncells) then
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p0 = p0 + 1
end do
end do
end do
end do

```

6 million iterations, for 16 processes  
1.6% overhead just from this loop  
23% in total

- Solution:
- Function call **once per batch**
- Batch size optimization

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## Overhead reduction:

### 2. Performance Model Similarities

```

do i = mm,m0,-1
z( jg(1,i,0), jg(2,i,0), jg(3,i,0) ) = -1.0D0
enddo

```



```

do i = mm,m1,-1
z( jg(1,i,1), jg(2,i,1), jg(3,i,1) ) = +1.0D0
enddo

```

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## Overhead reduction:



### 2. Performance Model Similarities

```
do i = mm, m0, -1
    z( jg(1,i,0), jg(2,i,0), jg(3,i,0) ) = -1.0D0
enddo
```

```
do i = mm, m1, -1
    z( jg(1,i,1), jg(2,i,1), jg(3,i,1) ) = +1.0D0
enddo
```

Loop 1:  $c_1 * (mm - m0)$     Loop 2:  $c_2 * (mm - m1)$

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## Overhead reduction:

### 2. Performance Model Similarities

```
do i = mm, m0, -1
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enddo
```

```
do i = mm, m1, -1
    z( jg(1,i,1), jg(2,i,1), jg(3,i,1) ) = +1.0D0
enddo
```

Loop 1:  $c_1 * (mm - m0)$     Loop 2:  $c_2 * (mm - m1)$

Solution:  
*Program Dependence Graph* based **similarity detection**  
 Model one loop **per** similarity group

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## Overhead reduction:

### 3. Regulate Frequency of model update

Models get more precise over time ON THE FLY

Solution:  
Prediction hit counter

**Delay** the next update using exponential backoff

$$q = b \cdot rand(0, 2^{h_c})$$

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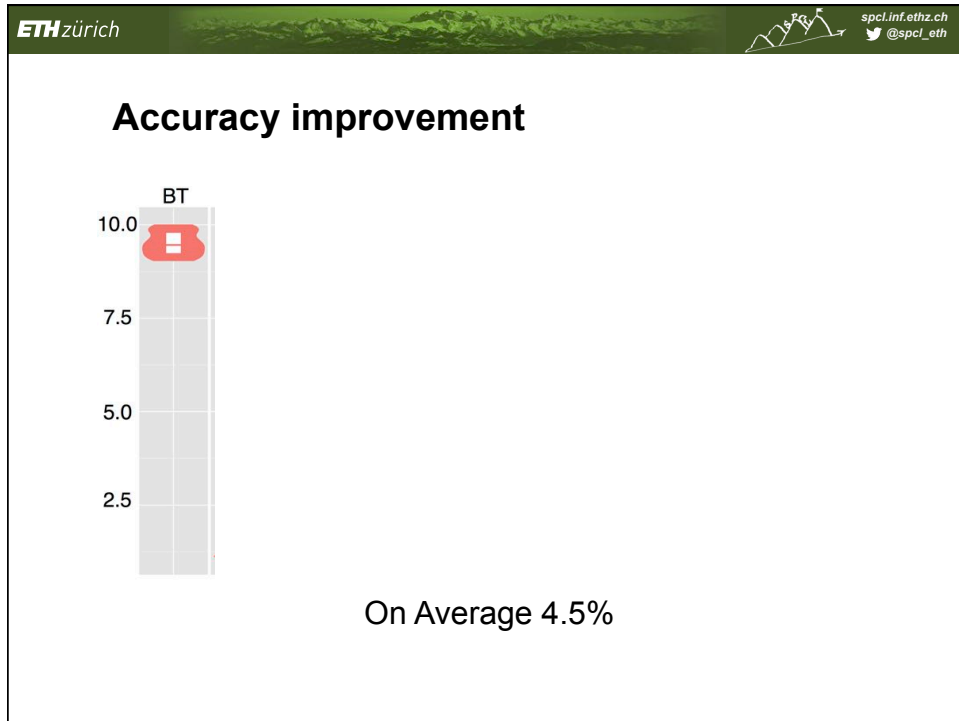
## Experimental Evaluation

- Measurement of Precision:
- PARS (Predicted adjusted R-square) (values between 0 - 1 )
- Lack of fit (LOF) (p-value < 0.05 tells better models are possible)
- Mean Overhead Reduction:
- Speedup
- LLN
- NAS
- Intel core i7 quad-core machine with 8GB RAM and 2-way multi-threaded

Precision

Overhead

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## Overhead reduction: 2. Performance Model Similarities

**What percentage of loops can we cluster?**

Best 50% (BT) , Worst 2% (kid\_su3\_rmd), Average 26%

**How precise is clustering?**

Best 100% (FT) , Worst 90% (kid\_su3\_rmd), Average 93%

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## Overhead reduction: 3. Regulate Frequency of model update

What percentage loops have changing behaviour?

Best gp\_quark\_prop – 8%  
Best MG – 0%

Average – 1.5%

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## Overhead Reduction

Method	%overhead compared to non-profiling
BT	~13.5
Dymm	~6.0
Hyper	~4.5
HyG	~4.0
Hy	~3.5
R	~3.0
Dy	~2.5

**On Average 25% reduction**

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## Conclusion

- Combine existing static and dynamic approaches
- Improve precision upto 10%
- Reduce overhead upto 65%
- Hope that low-overhead automatic model generation techniques will become popular to system engineers.

Accuracy improvement chart showing performance metrics for various models (BT, OS, EP, FT, SP, WP, IS, NP, LU, MG). The y-axis ranges from 25 to 100. Red circles indicate specific data points, and a red arrow points to a significant improvement in the SP model.



Overhead Reduction Overall bar chart showing overhead reduction for various models (BT, OS, EP, FT, SP, WP, IS, NP, LU, MG). The y-axis ranges from 0 to 100. Multiple colored bars represent different data series for each model, showing significant overhead reduction for several models.

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## Questions?

Aerial view of the ETH Zurich campus and surrounding city, showing the main building complex, the lake, and the mountains in the background.

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## Sample models

```
sum=0.0;
FORALLSITES (i, s) {
  for (dir=XUP; dir<=TUP; dir++)
    sum+= (double) ahmat_mag_sq (&(s->mom[dir]))
      -4.0;
}
```

$$f(P) = nx \cdot ny \cdot nz \cdot nt \cdot (1.56 \cdot TUP - 0.49 \cdot XUP + 0.45) + 0.001$$

<p>Previous approach:</p> <p>45 terms!! PARS of 0.75 p-value 0.01</p>	<p>New approach:</p> <p>PARS of 0.88 p-value 0.40</p>
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