## MPI: A Message-Passing Interface Standard Extension: Nonblocking Collective Operations (draft)

Message Passing Interface Forum

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### Chapter 5

### Collective Communication

#### 5.1 Introduction and Overview

Collective communication is defined as communication that involves a group or groups of processes. The functions of this type provided by MPI are the following:

• MPI\_ BARRIER: Barrier synchronization across all members of a group (Section 5.3).

- MPI\_ BCAST: Broadcast from one member to all members of a group (Section 5.4). This is shown as "broadcast" in Figure 5.1.
- MPI\_ GATHER, MPI\_ GATHERV: Gather data from all members of a group to one member (Section 5.5). This is shown as "gather" in Figure 5.1.
- MPI\_SCATTER, MPI\_SCATTERV: Scatter data from one member to all members of a group (Section 5.6). This is shown as "scatter" in Figure 5.1.
- MPI\_ ALLGATHER, MPI\_ ALLGATHERV: A variation on Gather where all members of a group receive the result (Section 5.7). This is shown as "allgather" in Figure 5.1.
- MPI\_ ALLTOALL, MPI\_ ALLTOALLV, MPI\_ ALLTOALLW: Scatter/Gather data from all members to all members of a group (also called complete exchange or all-to-all) (Section 5.8). This is shown as "alltoall" in Figure 5.1.
- MPI\_ ALLREDUCE, MPI\_ REDUCE: Global reduction operations such as sum, max, min, or user-defined functions, where the result is returned to all members of a group and a variation where the result is returned to only one member (Section 5.9).
- MPI\_REDUCE\_SCATTER: A combined reduction and scatter operation (Section 5.10).
- MPI\_ SCAN, MPI\_ EXSCAN: Scan across all members of a group (also called prefix) (Section 5.11).

One of the key arguments in a call to a collective routine is a communicator that defines the group or groups of participating processes and provides a context for the operation. This is discussed further in Section 5.2. The syntax and semantics of the collective operations are defined to be consistent with the syntax and semantics of the point-to-point operations. Thus, general datatypes are allowed and must match between sending and receiving processes as specified in Chapter ??. Several collective routines such as broadcast

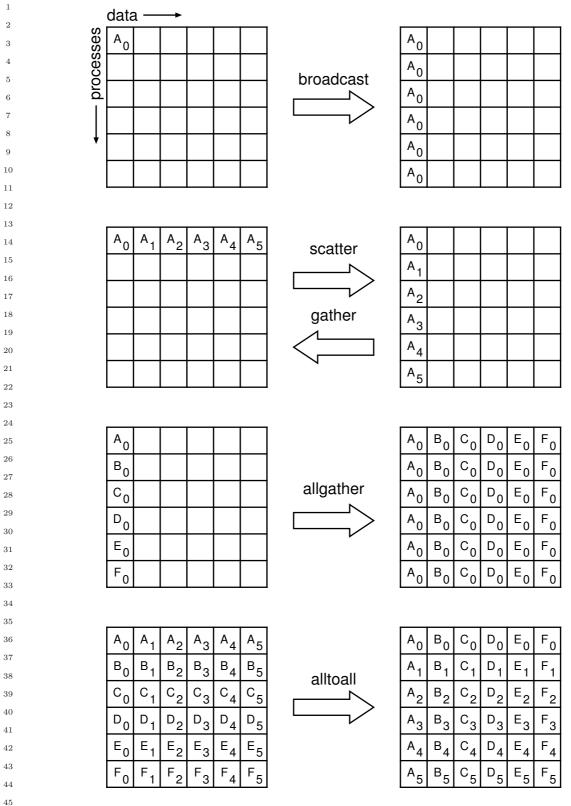


Figure 5.1: Collective move functions illustrated for a group of six processes. In each case, each row of boxes represents data locations in one process. Thus, in the broadcast, initially just the first process contains the data  $A_0$ , but after the broadcast all processes contain it.

and gather have a single originating or receiving process. Such a process is called the *root*. Some arguments in the collective functions are specified as "significant only at root," and are ignored for all participants except the root. The reader is referred to Chapter ?? for information concerning communication buffers, general datatypes and type matching rules, and to Chapter ?? for information on how to define groups and create communicators.

The type-matching conditions for the collective operations are more strict than the corresponding conditions between sender and receiver in point-to-point. Namely, for collective operations, the amount of data sent must exactly match the amount of data specified by the receiver. Different type maps (the layout in memory, see Section ??) between sender and receiver are still allowed. The collective operations do not have a message tag argument.

Collective routine calls operations can (but are not required to) return complete locally as soon as their the callers participation in the collective communication is complete finished. The local completion of a call collective operation indicates that the caller is now free to access locations in the communication buffer. It does not indicate that other processes in the group have completed or even started the operation (unless otherwise implied by in the description of the operation). Thus, a collective communication call may, or may not, have the effect of synchronizing all calling processes. This statement excludes, of course, the barrier function.

Collective communication calls may use the same communicators as point-to-point communication; MPI guarantees that messages generated on behalf of collective communication calls will not be confused with messages generated by point-to-point communication. A more detailed discussion of correct use of collective routines is found in Section 5.13.

Rationale. The equal-data restriction (on type matching) was made so as to avoid the complexity of providing a facility analogous to the status argument of MPI\_RECV for discovering the amount of data sent. Some of the collective routines would require an array of status values.

The statements about synchronization are made so as to allow a variety of implementations of the collective functions.

The collective operations do not accept a message tag argument. If future revisions of MPI define nonblocking collective functions, then tags (or a similar mechanism) might need to be added so as to allow the dis-ambiguation of multiple, pending, collective operations. (End of rationale.)

Advice to users. It is dangerous to rely on synchronization side-effects of the collective operations for program correctness. For example, even though a particular implementation may provide a broadcast routine with a side-effect of synchronization, the standard does not require this, and a program that relies on this will not be portable.

On the other hand, a correct, portable program must allow for the fact that a collective call may be synchronizing. Though one cannot rely on any synchronization side-effect, one must program so as to allow it. These issues are discussed further in Section 5.13. (*End of advice to users.*)

Advice to implementors. While vendors may write optimized collective routines matched to their architectures, a complete library of the collective communication routines can be written entirely using the MPI point-to-point communication functions and a few auxiliary functions. If implementing on top of point-to-point, a hidden,

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special communicator might be created for the collective operation so as to avoid interference with any on-going point-to-point communication at the time of the collective call. This is discussed further in Section 5.13. (End of advice to implementors.)

Many of the descriptions of the collective routines provide illustrations in terms of blocking MPI point-to-point routines. These are intended solely to indicate what data is sent or received by what process. Many of these examples are not correct MPI programs; for purposes of simplicity, they often assume infinite buffering.

#### 5.2 Communicator Argument

The key concept of the collective functions is to have a group or groups of participating processes. The routines do not have group identifiers as explicit arguments. Instead, there is a communicator argument. Groups and communicators are discussed in full detail in Chapter ??. For the purposes of this chapter, it is sufficient to know that there are two types of communicators: intra-communicators and inter-communicators. An intracommunicator can be thought of as an indentifier for a single group of processes linked with a context. An intercommunicator identifies two distinct groups of processes linked with a context.

#### Specifics for Intracommunicator Collective Operations

All processes in the group identified by the intracommunicator must call the collective routine with matching arguments.

In many cases, collective communication can occur "in place" for intracommunicators, with the output buffer being identical to the input buffer. This is specified by providing a special argument value, MPI\_IN\_PLACE, instead of the send buffer or the receive buffer argument, depending on the operation performed.

The "in place" operations are provided to reduce unnecessary memory motion by both the MPI implementation and by the user. Note that while the simple check of testing whether the send and receive buffers have the same address will work for some cases (e.g., MPI\_ALLREDUCE), they are inadequate in others (e.g., MPI\_GATHER, with root not equal to zero). Further, Fortran explicitly prohibits aliasing of arguments; the approach of using a special value to denote "in place" operation eliminates that difficulty. (End of rationale.)

Advice to users. By allowing the "in place" option, the receive buffer in many of the collective calls becomes a send-and-receive buffer. For this reason, a Fortran binding that includes INTENT must mark these as INOUT, not OUT.

Note that MPI\_IN\_PLACE is a special kind of value; it has the same restrictions on its use that MPI\_BOTTOM has.

Some intracommunicator collective operations do not support the "in place" option (e.g., MPI\_ALLTOALLV). (End of advice to users.)

#### 5.2.2 Applying Collective Operations to Intercommunicators

To understand how collective operations apply to intercommunicators, we can view most MPI intracommunicator collective operations as fitting one of the following categories (see, for instance, [6]):

All-To-All All processes contribute to the result. All processes receive the result.

- MPI\_ALLGATHER, MPI\_ALLGATHERV
- MPI\_ALLTOALL, MPI\_ALLTOALLV, MPI\_ALLTOALLW
- MPI\_ALLREDUCE, MPI\_REDUCE\_SCATTER

All-To-One All processes contribute to the result. One process receives the result.

- MPI\_GATHER, MPI\_GATHERV
- MPI\_REDUCE

One-To-All One process contributes to the result. All processes receive the result.

- MPI\_BCAST
- MPI\_SCATTER, MPI\_SCATTERV

Other Collective operations that do not fit into one of the above categories.

- MPI\_SCAN, MPI\_EXSCAN
- MPI\_BARRIER

The MPI\_BARRIER operation does not fit into this classification since no data is being moved (other than the implicit fact that a barrier has been called). The data movement patterns of MPI\_SCAN and MPI\_EXSCAN do not fit this taxonomy.

The application of collective communication to intercommunicators is best described in terms of two groups. For example, an all-to-all MPI\_ALLGATHER operation can be described as collecting data from all members of one group with the result appearing in all members of the other group (see Figure 5.2). As another example, a one-to-all MPI\_BCAST operation sends data from one member of one group to all members of the other group. Collective computation operations such as MPI\_REDUCE\_SCATTER have a similar interpretation (see Figure 5.3). For intracommunicators, these two groups are the same. For intercommunicators, these two groups are distinct. For the all-to-all operations, each such operation is described in two phases, so that it has a symmetric, full-duplex behavior.

The following collective operations also apply to intercommunicators:

- MPI\_BARRIER,
- MPI\_BCAST,
- MPI\_GATHER, MPI\_GATHERV,
- MPI\_SCATTER, MPI\_SCATTERV,
- MPI\_ALLGATHER, MPI\_ALLGATHERV,

- MPI\_ALLTOALL, MPI\_ALLTOALLV, MPI\_ALLTOALLW,
- MPI\_ALLREDUCE, MPI\_REDUCE,
- MPI\_REDUCE\_SCATTER.

In C++, the bindings for these functions are in the MPI::Comm class. However, since the collective operations do not make sense on a C++ MPI::Comm (as it is neither an intercommunicator nor an intracommunicator), the functions are all pure virtual.

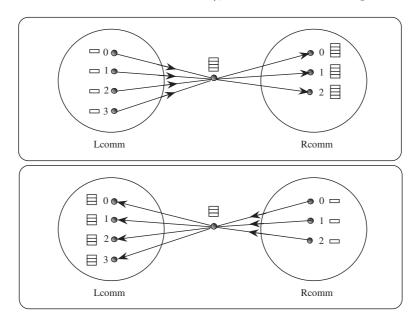


Figure 5.2: Intercommunicator allgather. The focus of data to one process is represented, not mandated by the semantics. The two phases do allgathers in both directions.

#### 5.2.3 Specifics for Intercommunicator Collective Operations

All processes in both groups identified by the intercommunicator must call the collective routine. In addition, processes in the same group must call the routine with matching arguments.

Note that the "in place" option for intracommunicators does not apply to intercommunicators since in the intercommunicator case there is no communication from a process to itself.

For intercommunicator collective communication, if the operation is rooted (e.g., broadcast, gather, scatter), then the transfer is unidirectional. The direction of the transfer is indicated by a special value of the root argument. In this case, for the group containing the root process, all processes in the group must call the routine using a special argument for the root. For this, the root process uses the special root value MPI\_ROOT; all other processes in the same group as the root use MPI\_PROC\_NULL. All processes in the other group (the group that is the remote group relative to the root process) must call the collective routine and provide the rank of the root. If the operation is unrooted (e.g., alltoall), then the transfer is bidirectional.

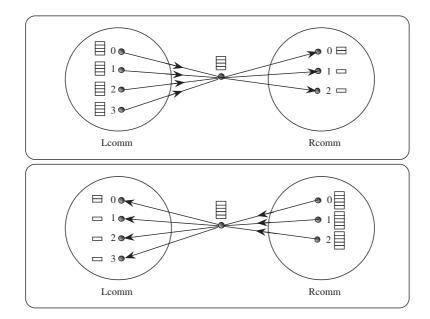


Figure 5.3: Intercommunicator reduce-scatter. The focus of data to one process is represented, not mandated by the semantics. The two phases do reduce-scatters in both directions.

Rationale. Rooted operations are unidirectional by nature, and there is a clear way of specifying direction. Non-rooted operations, such as all-to-all, will often occur as part of an exchange, where it makes sense to communicate in both directions at once. (End of rationale.)

#### 5.3 Barrier Synchronization

If comm is an intracommunicator, MPI\_BARRIER blocks the caller until all group members have called it. The call returns at any process only after all group members have entered the call.

If comm is an intercommunicator, the barrier is performed across all processes in the intercommunicator. In this case, all processes in one group (group A) of the intercommunicator may exit the barrier when all of the processes in the other group (group B) have entered the barrier.

#### 5.4 Broadcast

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```
MPI_BCAST( buffer, count, datatype, root, comm )
```

```
INOUT
            buffer
                                        starting address of buffer (choice)
 IN
            count
                                        number of entries in buffer (non-negative integer)
 IN
                                        data type of buffer (handle)
            datatype
 IN
                                       rank of broadcast root (integer)
            root
 IN
            comm
                                        communicator (handle)
int MPI_Bcast(void* buffer, int count, MPI_Datatype datatype, int root,
               MPI_Comm comm )
MPI_BCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, IERROR)
    <type> BUFFER(*)
    INTEGER COUNT, DATATYPE, ROOT, COMM, IERROR
```

If comm is an intracommunicator, MPI\_BCAST broadcasts a message from the process with rank root to all processes of the group, itself included. It is called by all members of the group using the same arguments for comm and root. On return, the content of root's buffer is copied to all other processes.

General, derived datatypes are allowed for datatype. The type signature of count, datatype on any process must be equal to the type signature of count, datatype at the root. This implies that the amount of data sent must be equal to the amount received, pairwise between each process and the root. MPI\_BCAST and all other data-movement collective routines make this restriction. Distinct type maps between sender and receiver are still allowed.

The "in place" option is not meaningful here.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is broadcast from the root to all processes in group B. The buffer arguments of the processes in group B must be consistent with the buffer argument of the root.

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#### 5.4.1 Example using MPI\_BCAST

The examples in this section use intracommunicators.

**Example 5.1** Broadcast 100 ints from process 0 to every process in the group.

```
MPI_Comm comm;
int array[100];
```

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```
int root=0;
...
MPI_Bcast( array, 100, MPI_INT, root, comm);
```

As in many of our example code fragments, we assume that some of the variables (such as comm in the above) have been assigned appropriate values.

#### 5.5 Gather

MPI\_GATHER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	recvcount	number of elements for any single receive (non-negative integer, significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)

MPI\_GATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR

If comm is an intracommunicator, each process (root process included) sends the contents of its send buffer to the root process. The root process receives the messages and stores them in rank order. The outcome is as if each of the n processes in the group (including the root process) had executed a call to

```
MPI_Send(sendbuf, sendcount, sendtype, root, ...),

and the root had executed n calls to

MPI_Recv(recvbuf + i · recvcount · extent(recvtype), recvcount, recvtype, i, ...),

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```

where extent(recvtype) is the type extent obtained from a call to MPI\_Type\_extent().

An alternative description is that the n messages sent by the processes in the group are concatenated in rank order, and the resulting message is received by the root as if by a call to MPI\_RECV(recvbuf, recvcount·n, recvtype, ...).

The receive buffer is ignored for all non-root processes.

General, derived datatypes are allowed for both sendtype and recvtype. The type signature of sendcount, sendtype on each process must be equal to the type signature of recvcount, recvtype at the root. This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process root, while on other processes, only arguments sendbuf, sendcount, sendtype, root, and comm are significant. The arguments root and comm must have identical values on all processes.

The specification of counts and types should not cause any location on the root to be written more than once. Such a call is erroneous.

Note that the recvcount argument at the root indicates the number of items it receives from *each* process, not the total number of items it receives.

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE as the value of sendbuf at the root. In such a case, sendcount and sendtype are ignored, and the contribution of the root to the gathered vector is assumed to be already in the correct place in the receive buffer.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is gathered from all processes in group B to the root. The send buffer arguments of the processes in group B must be consistent with the receive buffer argument of the root.

MPI\_GATHERV( sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs, recvtype, root, comm)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative inte-
		$\operatorname{ger})$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at
		root)

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IN	recvcounts	non-negative integer array (of length group size) containing the number of elements that are received from each process (significant only at root)
IN	displs	integer array (of length group size). Entry i specifies the displacement relative to recvbuf at which to place the incoming data from process i (significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)

```
MPI_GATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS, RECVTYPE, ROOT, COMM, IERROR)
```

```
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT,
COMM, IERROR
```

MPI\_GATHERV extends the functionality of MPI\_GATHER by allowing a varying count of data from each process, since recvcounts is now an array. It also allows more flexibility as to where the data is placed on the root, by providing the new argument, displs.

If comm is an intracommunicator, the outcome is as if each process, including the root process, sends a message to the root,

```
MPI_Send(sendbuf, sendcount, sendtype, root, ...),
```

and the root executes n receives,

```
MPI_Recv(recvbuf + displs[j] \cdot extent(recvtype), recvcounts[j], recvtype, i, ...).
```

The data received from process j is placed into recvbuf of the root process beginning at offset displs[j] elements (in terms of the recvtype).

The receive buffer is ignored for all non-root processes.

The type signature implied by sendcount, sendtype on process i must be equal to the type signature implied by recvcounts[i], recvtype at the root. This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed, as illustrated in Example 5.6.

All arguments to the function are significant on process root, while on other processes, only arguments sendbuf, sendcount, sendtype, root, and comm are significant. The arguments root and comm must have identical values on all processes.

 The specification of counts, types, and displacements should not cause any location on the root to be written more than once. Such a call is erroneous.

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE as the value of sendbuf at the root. In such a case, sendcount and sendtype are ignored, and the contribution of the root to the gathered vector is assumed to be already in the correct place in the receive buffer

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is gathered from all processes in group B to the root. The send buffer arguments of the processes in group B must be consistent with the receive buffer argument of the root.

#### 5.5.1 Examples using MPI\_GATHER, MPI\_GATHERV

The examples in this section use intracommunicators.

**Example 5.2** Gather 100 ints from every process in group to root. See figure 5.4.

```
MPI_Comm comm;
int gsize,sendarray[100];
int root, *rbuf;
...
MPI_Comm_size( comm, &gsize);
rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Gather( sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

**Example 5.3** Previous example modified – only the root allocates memory for the receive buffer.

```
MPI_Comm comm;
int gsize,sendarray[100];
int root, myrank, *rbuf;
...
MPI_Comm_rank( comm, &myrank);
if ( myrank == root) {
    MPI_Comm_size( comm, &gsize);
    rbuf = (int *)malloc(gsize*100*sizeof(int));
}
MPI_Gather( sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

**Example 5.4** Do the same as the previous example, but use a derived datatype. Note that the type cannot be the entire set of gsize\*100 ints since type matching is defined pairwise between the root and each process in the gather.

```
MPI_Comm comm;
int gsize,sendarray[100];
```

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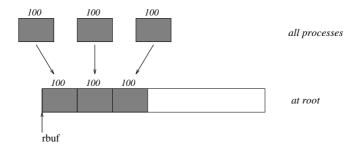


Figure 5.4: The root process gathers 100 ints from each process in the group.

```
int root, *rbuf;
MPI_Datatype rtype;
...
MPI_Comm_size( comm, &gsize);
MPI_Type_contiguous( 100, MPI_INT, &rtype );
MPI_Type_commit( &rtype );
rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Gather( sendarray, 100, MPI_INT, rbuf, 1, rtype, root, comm);
```

Example 5.5 Now have each process send 100 ints to root, but place each set (of 100) stride ints apart at receiving end. Use MPI\_GATHERV and the displs argument to achieve this effect. Assume  $stride \ge 100$ . See Figure 5.5.

```
MPI_Comm comm;
int gsize,sendarray[100];
int root, *rbuf, stride;
int *displs,i,*rcounts;
...

MPI_Comm_size( comm, &gsize);
rbuf = (int *)malloc(gsize*stride*sizeof(int));
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    rcounts[i] = 100;
}
MPI_Gatherv( sendarray, 100, MPI_INT, rbuf, rcounts, displs, MPI_INT, root, comm);</pre>
```

Note that the program is erroneous if stride < 100.

**Example 5.6** Same as Example 5.5 on the receiving side, but send the 100 ints from the 0th column of a  $100 \times 150$  int array, in C. See Figure 5.6.

```
MPI_Comm comm;
```

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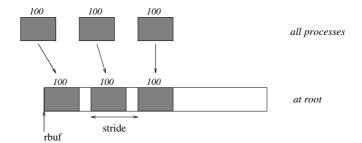


Figure 5.5: The root process gathers 100 ints from each process in the group, each set is placed stride ints apart.

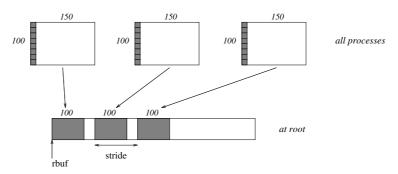


Figure 5.6: The root process gathers column 0 of a  $100 \times 150$  C array, and each set is placed stride ints apart.

```
int gsize, sendarray[100][150];
int root, *rbuf, stride;
MPI_Datatype stype;
int *displs,i,*rcounts;
MPI_Comm_size( comm, &gsize);
rbuf = (int *)malloc(gsize*stride*sizeof(int));
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    rcounts[i] = 100;
}
/* Create datatype for 1 column of array
MPI_Type_vector( 100, 1, 150, MPI_INT, &stype);
MPI_Type_commit( &stype );
MPI_Gatherv( sendarray, 1, stype, rbuf, rcounts, displs, MPI_INT,
                                                          root, comm);
```

Example 5.7 Process i sends (100-i) ints from the i-th column of a  $100 \times 150$  int

5.5. GATHER 15

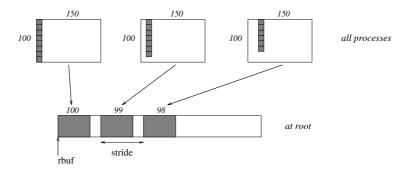


Figure 5.7: The root process gathers 100-i ints from column i of a 100×150 C array, and each set is placed stride ints apart.

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array, in C. It is received into a buffer with stride, as in the previous two examples. See Figure 5.7.

```
MPI_Comm comm;
int gsize,sendarray[100][150],*sptr;
int root, *rbuf, stride, myrank;
MPI_Datatype stype;
int *displs,i,*rcounts;
MPI_Comm_size( comm, &gsize);
MPI_Comm_rank( comm, &myrank );
rbuf = (int *)malloc(gsize*stride*sizeof(int));
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    rcounts[i] = 100-i;
                            /* note change from previous example */
}
/* Create datatype for the column we are sending
MPI_Type_vector( 100-myrank, 1, 150, MPI_INT, &stype);
MPI_Type_commit( &stype );
/* sptr is the address of start of "myrank" column
 */
sptr = &sendarray[0][myrank];
MPI_Gatherv( sptr, 1, stype, rbuf, rcounts, displs, MPI_INT,
                                                     root, comm);
```

Note that a different amount of data is received from each process.

**Example 5.8** Same as Example 5.7, but done in a different way at the sending end. We create a datatype that causes the correct striding at the sending end so that we read a column of a C array. A similar thing was done in Example ??, Section ??.

\*/

```
1
         MPI_Comm comm;
2
         int gsize,sendarray[100][150],*sptr;
3
         int root, *rbuf, stride, myrank, disp[2], blocklen[2];
4
         MPI_Datatype stype,type[2];
         int *displs,i,*rcounts;
6
         . . .
9
         MPI_Comm_size( comm, &gsize);
10
         MPI_Comm_rank( comm, &myrank );
11
         rbuf = (int *)malloc(gsize*stride*sizeof(int));
12
         displs = (int *)malloc(gsize*sizeof(int));
13
         rcounts = (int *)malloc(gsize*sizeof(int));
         for (i=0; i<gsize; ++i) {
15
             displs[i] = i*stride;
16
             rcounts[i] = 100-i;
17
         }
18
         /* Create datatype for one int, with extent of entire row
19
          */
         disp[0] = 0;
                             disp[1] = 150*sizeof(int);
21
         type[0] = MPI_INT; type[1] = MPI_UB;
22
         blocklen[0] = 1;
                             blocklen[1] = 1;
23
         MPI_Type_struct( 2, blocklen, disp, type, &stype );
24
         MPI_Type_commit( &stype );
25
         sptr = &sendarray[0][myrank];
         MPI_Gatherv( sptr, 100-myrank, stype, rbuf, rcounts, displs, MPI_INT,
27
                                                                        root, comm);
28
29
     Example 5.9 Same as Example 5.7 at sending side, but at receiving side we make the
30
     stride between received blocks vary from block to block. See Figure 5.8.
31
         MPI_Comm comm;
33
         int gsize,sendarray[100][150],*sptr;
34
         int root, *rbuf, *stride, myrank, bufsize;
35
         MPI_Datatype stype;
         int *displs,i,*rcounts,offset;
         . . .
39
40
         MPI_Comm_size( comm, &gsize);
41
         MPI_Comm_rank( comm, &myrank );
42
         stride = (int *)malloc(gsize*sizeof(int));
44
45
         /* stride[i] for i = 0 to gsize-1 is set somehow
46
```

5.5. GATHER 17

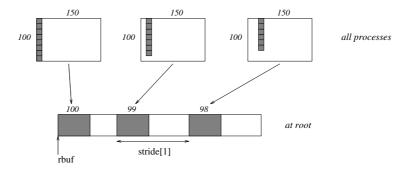


Figure 5.8: The root process gathers 100-i ints from column i of a 100×150 C array, and each set is placed stride[i] ints apart (a varying stride).

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```
/* set up displs and rounts vectors first
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
offset = 0;
for (i=0; i<gsize; ++i) {
    displs[i] = offset;
    offset += stride[i];
    rcounts[i] = 100-i;
}
/* the required buffer size for rbuf is now easily obtained
 */
bufsize = displs[gsize-1]+rcounts[gsize-1];
rbuf = (int *)malloc(bufsize*sizeof(int));
/* Create datatype for the column we are sending
 */
MPI_Type_vector( 100-myrank, 1, 150, MPI_INT, &stype);
MPI_Type_commit( &stype );
sptr = &sendarray[0][myrank];
MPI_Gatherv( sptr, 1, stype, rbuf, rcounts, displs, MPI_INT,
                                                     root, comm);
```

**Example 5.10** Process i sends num ints from the i-th column of a  $100 \times 150$  int array, in C. The complicating factor is that the various values of num are not known to root, so a separate gather must first be run to find these out. The data is placed contiguously at the receiving end.

```
MPI_Comm comm;
int gsize,sendarray[100][150],*sptr;
int root, *rbuf, stride, myrank, disp[2], blocklen[2];
MPI_Datatype stype,types[2];
int *displs,i,*rcounts,num;

48
```

```
1
2
         MPI_Comm_size( comm, &gsize);
3
         MPI_Comm_rank( comm, &myrank );
4
5
         /* First, gather nums to root
6
          */
         rcounts = (int *)malloc(gsize*sizeof(int));
         MPI_Gather( &num, 1, MPI_INT, roounts, 1, MPI_INT, root, comm);
         /* root now has correct rounts, using these we set displs[] so
10
          * that data is placed contiguously (or concatenated) at receive end
11
          */
12
         displs = (int *)malloc(gsize*sizeof(int));
13
         displs[0] = 0;
         for (i=1; i<gsize; ++i) {
15
             displs[i] = displs[i-1]+rcounts[i-1];
16
         }
17
         /* And, create receive buffer
18
          */
19
         rbuf = (int *)malloc(gsize*(displs[gsize-1]+rcounts[gsize-1])
                                                                     *sizeof(int));
21
         /* Create datatype for one int, with extent of entire row
22
          */
23
         disp[0] = 0;
                             disp[1] = 150*sizeof(int);
24
         type[0] = MPI_INT; type[1] = MPI_UB;
25
         blocklen[0] = 1; blocklen[1] = 1;
         MPI_Type_struct( 2, blocklen, disp, type, &stype );
27
         MPI_Type_commit( &stype );
28
         sptr = &sendarray[0][myrank];
29
         MPI_Gatherv( sptr, num, stype, rbuf, rcounts, displs, MPI_INT,
30
                                                                       root, comm);
33
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```

5.6. SCATTER 19

#### 5.6 Scatter

MPI\_SCATTER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN	sendbuf	${\it address\ of\ send\ buffer\ (choice,\ significant\ only\ at\ root)}$
IN	sendcount	number of elements sent to each process (non-negative integer, significant only at root)
IN	sendtype	data type of send buffer elements (significant only at root) (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements in receive buffer (non-negative integer) $$
IN	recvtype	data type of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)

MPI\_SCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR

MPI\_SCATTER is the inverse operation to MPI\_GATHER.

If comm is an intracommunicator, the outcome is as if the root executed n send operations,

$$\label{eq:mpi_send} \begin{split} \texttt{MPI\_Send}(\texttt{sendbuf} + \texttt{i} \cdot \texttt{sendcount} \cdot \texttt{extent}(\texttt{sendtype}), \texttt{sendcount}, \texttt{sendtype}, \texttt{i}, ...), \\ \text{and each process executed a receive,} \end{split}$$

```
MPI_Recv(recvbuf, recvcount, recvtype, i, ...).
```

An alternative description is that the root sends a message with MPI\_Send(sendbuf, sendcount·n, sendtype, ...). This message is split into n equal segments, the i-th segment is sent to the i-th process in the group, and each process receives this message as above.

The send buffer is ignored for all non-root processes.

The type signature associated with sendcount, sendtype at the root must be equal to the type signature associated with recvcount, recvtype at all processes (however, the type maps may be different). This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process root, while on other processes, only arguments recvbuf, recvcount, recvtype, root, and comm are significant. The arguments root and comm must have identical values on all processes.

The specification of counts and types should not cause any location on the root to be read more than once.

Rationale. Though not needed, the last restriction is imposed so as to achieve symmetry with MPI\_GATHER, where the corresponding restriction (a multiple-write restriction) is necessary. (End of rationale.)

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE as the value of recvbuf at the root. In such case, recvcount and recvtype are ignored, and root "sends" no data to itself. The scattered vector is still assumed to contain n segments, where n is the group size; the *root*-th segment, which root should "send to itself," is not moved.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is scattered from the root to all processes in group B. The receive buffer arguments of the processes in group B must be consistent with the send buffer argument of the root.

MPI\_SCATTERV( sendbuf, sendcounts, displs, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN IN	sendbuf sendcounts	address of send buffer (choice, significant only at root) non-negative integer array (of length group size) specifying the number of elements to send to each processor
IN	displs	integer array (of length group size). Entry ${\tt i}$ specifies the displacement (relative to ${\tt sendbuf}$ ) from which to take the outgoing data to process ${\tt i}$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements in receive buffer (non-negative integer) ${\bf r}$
IN	recvtype	data type of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)

MPI\_SCATTERV(SENDBUF, SENDCOUNTS, DISPLS, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR)

5.6. SCATTER 21

```
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, RECVCOUNT, RECVTYPE, ROOT,
COMM, IERROR
```

MPI\_SCATTERV is the inverse operation to MPI\_GATHERV.

MPI\_SCATTERV extends the functionality of MPI\_SCATTER by allowing a varying count of data to be sent to each process, since sendcounts is now an array. It also allows more flexibility as to where the data is taken from on the root, by providing an additional argument, displs.

If comm is an intracommunicator, the outcome is as if the root executed n send operations,

```
\label{eq:mpi_send} \begin{split} \texttt{MPI\_Send}(\texttt{sendbuf} + \texttt{displs}[\texttt{i}] \cdot \texttt{extent}(\texttt{sendtype}), \texttt{sendcounts}[\texttt{i}], \texttt{sendtype}, \texttt{i}, ...), \\ \text{and each process executed a receive,} \end{split}
```

```
MPI_Recv(recvbuf, recvcount, recvtype, i, ...).
```

The send buffer is ignored for all non-root processes.

The type signature implied by sendcount[i], sendtype at the root must be equal to the type signature implied by recvcount, recvtype at process i (however, the type maps may be different). This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process root, while on other processes, only arguments recvbuf, recvcount, recvtype, root, and comm are significant. The arguments root and comm must have identical values on all processes.

The specification of counts, types, and displacements should not cause any location on the root to be read more than once.

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE as the value of recvbuf at the root. In such case, recvcount and recvtype are ignored, and root "sends" no data to itself. The scattered vector is still assumed to contain n segments, where n is the group size; the *root*-th segment, which root should "send to itself," is not moved.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is scattered from the root to all processes in group B. The receive buffer arguments of the processes in group B must be consistent with the send buffer argument of the root.

#### 5.6.1 Examples using MPI\_SCATTER, MPI\_SCATTERV

The examples in this section use intracommunicators.

**Example 5.11** The reverse of Example 5.2. Scatter sets of 100 ints from the root to each process in the group. See Figure 5.9.

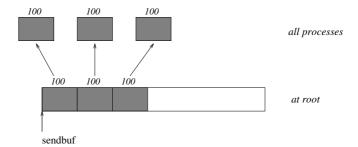


Figure 5.9: The root process scatters sets of 100 ints to each process in the group.

```
MPI_Comm comm;
int gsize,*sendbuf;
int root, rbuf[100];
...
MPI_Comm_size( comm, &gsize);
sendbuf = (int *)malloc(gsize*100*sizeof(int));
...
MPI_Scatter( sendbuf, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

**Example 5.12** The reverse of Example 5.5. The root process scatters sets of 100 ints to the other processes, but the sets of 100 are *stride ints* apart in the sending buffer. Requires use of MPI\_SCATTERV. Assume  $stride \ge 100$ . See Figure 5.10.

```
MPI_Comm comm;
int gsize,*sendbuf;
int root, rbuf[100], i, *displs, *scounts;

...

MPI_Comm_size( comm, &gsize);
sendbuf = (int *)malloc(gsize*stride*sizeof(int));
...
displs = (int *)malloc(gsize*sizeof(int));
scounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    scounts[i] = 100;
}
MPI_Scatterv( sendbuf, scounts, displs, MPI_INT, rbuf, 100, MPI_INT, root, comm);</pre>
```

**Example 5.13** The reverse of Example 5.9. We have a varying stride between blocks at sending (root) side, at the receiving side we receive into the i-th column of a  $100 \times 150$  C array. See Figure 5.11.

```
MPI_Comm comm;
```

5.6. SCATTER 23

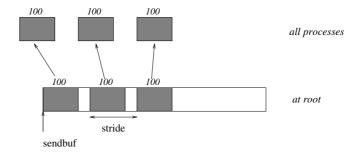


Figure 5.10: The root process scatters sets of 100 ints, moving by stride ints from send to send in the scatter.

10

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```
int gsize,recvarray[100][150],*rptr;
                                                                               13
int root, *sendbuf, myrank, bufsize, *stride;
MPI_Datatype rtype;
int i, *displs, *scounts, offset;
                                                                               16
                                                                               17
MPI_Comm_size( comm, &gsize);
                                                                               18
MPI_Comm_rank( comm, &myrank );
                                                                               19
stride = (int *)malloc(gsize*sizeof(int));
                                                                               21
                                                                               22
/* stride[i] for i = 0 to gsize-1 is set somehow
                                                                               23
 * sendbuf comes from elsewhere
                                                                               24
 */
displs = (int *)malloc(gsize*sizeof(int));
scounts = (int *)malloc(gsize*sizeof(int));
                                                                               28
offset = 0;
                                                                               29
for (i=0; i<gsize; ++i) {
                                                                               30
    displs[i] = offset;
    offset += stride[i];
    scounts[i] = 100 - i;
                                                                               33
}
                                                                               34
/* Create datatype for the column we are receiving
                                                                               35
MPI_Type_vector( 100-myrank, 1, 150, MPI_INT, &rtype);
MPI_Type_commit( &rtype );
rptr = &recvarray[0][myrank];
                                                                               39
MPI_Scatterv( sendbuf, scounts, displs, MPI_INT, rptr, 1, rtype,
                                                                               40
                                                           root, comm);
                                                                               41
```

Figure 5.11: The root scatters blocks of 100-i ints into column i of a 100×150 C array. At the sending side, the blocks are stride[i] ints apart.

#### 5.7 Gather-to-all

MPI\_ALLGATHER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements received from any process (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

MPI\_ALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, IERROR

MPI\_ALLGATHER can be thought of as MPI\_GATHER, but where all processes receive the result, instead of just the root. The block of data sent from the j-th process is received by every process and placed in the j-th block of the buffer recvbuf.

The type signature associated with sendcount, sendtype, at a process must be equal to the type signature associated with recvcount, recvtype at any other process.

If comm is an intracommunicator, the outcome of a call to MPI\_ALLGATHER(...) is as if all processes executed n calls to

for  $\mathtt{root} = 0$ , ...,  $\mathtt{n-1}$ . The rules for correct usage of MPI\_ALLGATHER are easily found from the corresponding rules for MPI\_GATHER.

The "in place" option for intracommunicators is specified by passing the value MPI\_IN\_PLACE to the argument sendbuf at all processes. sendcount and sendtype are ignored. Then the input data of each process is assumed to be in the area where that process would receive its own contribution to the receive buffer.

If comm is an intercommunicator, then each process in group A contributes a data item; these items are concatenated and the result is stored at each process in group B. Conversely the concatenation of the contributions of the processes in group B is stored at each process in group A. The send buffer arguments in group A must be consistent with the receive buffer arguments in group B, and vice versa.

Advice to users. The communication pattern of MPI\_ALLGATHER executed on an intercommunication domain need not be symmetric. The number of items sent by processes in group A (as specified by the arguments sendcount, sendtype in group A and the arguments recvcount, recvtype in group B), need not equal the number of items sent by processes in group B (as specified by the arguments sendcount, sendtype in group B and the arguments recvcount, recvtype in group A). In particular, one can move data in only one direction by specifying sendcount = 0 for the communication in the reverse direction.

(End of advice to users.)

#### MPI\_ALLGATHERV( sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs, recvtype, comm)

IN IN	sendbuf sendcount	starting address of send buffer (choice) number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcounts	non-negative integer array (of length group size) containing the number of elements that are received from each process
IN	displs	integer array (of length group size). Entry <b>i</b> specifies the displacement (relative to recvbuf) at which to place the incoming data from process <b>i</b>
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

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41 42

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```
MPI_Datatype recvtype, MPI_Comm comm)
    MPI_ALLGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
3
                  RECVTYPE, COMM, IERROR)
4
         <type> SENDBUF(*), RECVBUF(*)
         INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, COMM,
         IERROR
    void MPI::Comm::Allgatherv(const void* sendbuf, int sendcount, const
                  MPI::Datatype& sendtype, void* recvbuf,
10
                  const int recvcounts[], const int displs[],
11
                  const MPI::Datatype& recvtype) const = 0
12
```

MPI\_ALLGATHERV can be thought of as MPI\_GATHERV, but where all processes receive the result, instead of just the root. The block of data sent from the j-th process is received by every process and placed in the j-th block of the buffer recvbuf. These blocks need not all be the same size.

The type signature associated with sendcount, sendtype, at process j must be equal to the type signature associated with recvcounts[j], recvtype at any other process.

If comm is an intracommunicator, the outcome is as if all processes executed calls to

```
MPI_GATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs,
                                                  recvtype,root,comm),
```

for root = 0, ..., n-1. The rules for correct usage of MPI\_ALLGATHERV are easily found from the corresponding rules for MPI\_GATHERV.

The "in place" option for intracommunicators is specified by passing the value MPI\_IN\_PLACE to the argument sendbuf at all processes. sendcount and sendtype are ignored. Then the input data of each process is assumed to be in the area where that process would receive its own contribution to the receive buffer.

If comm is an intercommunicator, then each process in group A contributes a data item; these items are concatenated and the result is stored at each process in group B. Conversely the concatenation of the contributions of the processes in group B is stored at each process in group A. The send buffer arguments in group A must be consistent with the receive buffer arguments in group B, and vice versa.

#### Examples using MPI\_ALLGATHER, MPI\_ALLGATHERV

The examples in this section use intracommunicators.

**Example 5.14** The all-gather version of Example 5.2. Using MPI\_ALLGATHER, we will gather 100 ints from every process in the group to every process.

```
MPI_Comm comm;
int gsize, sendarray[100];
int *rbuf;
. . .
MPI_Comm_size( comm, &gsize);
rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Allgather( sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, comm);
```

After the call, every process has the group-wide concatenation of the sets of data.

#### 5.8 All-to-All Scatter/Gather

MPI\_ALLTOALL(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements sent to each process (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements received from any process (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

MPI\_ALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, IERROR

MPI\_ALLTOALL is an extension of MPI\_ALLGATHER to the case where each process sends distinct data to each of the receivers. The j-th block sent from process i is received by process j and is placed in the i-th block of recvbuf.

The type signature associated with sendcount, sendtype, at a process must be equal to the type signature associated with recvcount, recvtype at any other process. This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. As usual, however, the type maps may be different.

If comm is an intracommunicator, the outcome is as if each process executed a send to each process (itself included) with a call to,

$$\label{eq:mpi_send} \begin{split} \texttt{MPI\_Send}(\texttt{sendbuf} + \texttt{i} \cdot \texttt{sendcount} \cdot \texttt{extent}(\texttt{sendtype}), \texttt{sendcount}, \texttt{sendtype}, \texttt{i}, ...), \\ \text{and a receive from every other process with a call to,} \end{split}$$

```
\mathtt{MPI\_Recv}(\mathtt{recvbuf} + \mathtt{i} \cdot \mathtt{recvcount} \cdot \mathtt{extent}(\mathtt{recvtype}), \mathtt{recvcount}, \mathtt{recvtype}, \mathtt{i}, ...).
```

All arguments on all processes are significant. The argument comm must have identical values on all processes.

No "in place" option is supported.

If comm is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The j-th send buffer of process

45

46

47

1 i in group A should be consistent with the i-th receive buffer of process j in group B, and 2 vice versa. 3 Advice to users. When all-to-all is executed on an intercommunication domain, then 4 the number of data items sent from processes in group A to processes in group B need 5 not equal the number of items sent in the reverse direction. In particular, one can have 6 unidirectional communication by specifying sendcount = 0 in the reverse direction. (End of advice to users.) 9 10 11 MPI\_ALLTOALLV(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcounts, rdispls, recv-12 type, comm) 13 14 IN sendbuf starting address of send buffer (choice) 15 IN sendcounts non-negative integer array equal to the group size spec-16 ifying the number of elements to send to each proces-17 sor 18 IN sdispls integer array (of length group size). Entry j specifies 19 the displacement (relative to sendbuf) from which to 20 take the outgoing data destined for process j 21 22 IN sendtype data type of send buffer elements (handle) 23 recvbuf OUT address of receive buffer (choice) 24 IN recvcounts non-negative integer array equal to the group size spec-25 ifying the number of elements that can be received 26 from each processor 27 28 IN rdispls integer array (of length group size). Entry i speci-29 fies the displacement (relative to recvbuf) at which to 30 place the incoming data from process i 31 IN data type of receive buffer elements (handle) recvtype 32 IN comm communicator (handle) 33 34 35 int MPI\_Alltoallv(void\* sendbuf, int \*sendcounts, int \*sdispls, 36 MPI\_Datatype sendtype, void\* recvbuf, int \*recvcounts, 37 int \*rdispls, MPI\_Datatype recvtype, MPI\_Comm comm) 38 MPI\_ALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, RECVCOUNTS, 39 RDISPLS, RECVTYPE, COMM, IERROR) 40 <type> SENDBUF(\*), RECVBUF(\*) 41 INTEGER SENDCOUNTS(\*), SDISPLS(\*), SENDTYPE, RECVCOUNTS(\*), RDISPLS(\*), 42

INTEGER SENDCOUNTS(\*), SDISPLS(\*), SENDTYPE, RECVCOUNTS(\*), RDISPLS(\*), RECVTYPE, COMM, IERROR

MPI\_ALLTOALLV adds flexibility to MPI\_ALLTOALL in that the location of data for the send is specified by sdispls and the location of the placement of the data on the receive side is specified by rdispls.

If comm is an intracommunicator, then the j-th block sent from process i is received by process j and is placed in the i-th block of recvbuf. These blocks need not all have the same size.

The type signature associated with sendcount[j], sendtype at process i must be equal to the type signature associated with recvcount[i], recvtype at process j. This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. Distinct type maps between sender and receiver are still allowed.

The outcome is as if each process sent a message to every other process with,

$$\label{eq:mpi_send} \begin{split} \texttt{MPI\_Send}(\texttt{sendbuf} + \texttt{displs}[\texttt{i}] \cdot \texttt{extent}(\texttt{sendtype}), \texttt{sendcounts}[\texttt{i}], \texttt{sendtype}, \texttt{i}, ...), \\ \text{and received a message from every other process with a call to} \end{split}$$

```
\texttt{MPI\_Recv}(\texttt{recvbuf} + \texttt{displs}[\texttt{i}] \cdot \texttt{extent}(\texttt{recvtype}), \texttt{recvcounts}[\texttt{i}], \texttt{recvtype}, \texttt{i}, \ldots).
```

All arguments on all processes are significant. The argument comm must have identical values on all processes.

No "in place" option is supported.

If comm is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The j-th send buffer of process i in group A should be consistent with the i-th receive buffer of process j in group B, and vice versa.

Rationale. The definitions of MPI\_ALLTOALL and MPI\_ALLTOALLV give as much flexibility as one would achieve by specifying n independent, point-to-point communications, with two exceptions: all messages use the same datatype, and messages are scattered from (or gathered to) sequential storage. (*End of rationale*.)

Advice to implementors. Although the discussion of collective communication in terms of point-to-point operation implies that each message is transferred directly from sender to receiver, implementations may use a tree communication pattern. Messages can be forwarded by intermediate nodes where they are split (for scatter) or concatenated (for gather), if this is more efficient. (End of advice to implementors.)

```
1
     MPI_ALLTOALLW(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcounts, rdispls, recv-
2
     types, comm)
3
       IN
                  sendbuf
                                               starting address of send buffer (choice)
4
       IN
                  sendcounts
                                               integer array equal to the group size specifying the
5
                                               number of elements to send to each processor (array
6
                                               of non-negative integers)
       IN
                  sdispls
                                               integer array (of length group size). Entry j specifies
9
                                               the displacement in bytes (relative to sendbuf) from
10
                                               which to take the outgoing data destined for process
11
                                               j (array of integers)
12
       IN
                  sendtypes
                                               array of datatypes (of length group size). Entry j
13
                                               specifies the type of data to send to process j (array
14
                                               of handles)
15
       OUT
                  recvbuf
                                               address of receive buffer (choice)
16
17
       IN
                  recvcounts
                                               integer array equal to the group size specifying the
18
                                               number of elements that can be received from each
19
                                               processor (array of non-negative integers)
       IN
                  rdispls
                                               integer array (of length group size). Entry i specifies
21
                                               the displacement in bytes (relative to recvbuf) at which
22
                                               to place the incoming data from process i (array of
23
                                               integers)
24
       IN
                  recvtypes
                                               array of datatypes (of length group size). Entry i
25
                                               specifies the type of data received from process i (ar-
                                               ray of handles)
27
28
       IN
                  comm
                                               communicator (handle)
29
30
     int MPI_Alltoallw(void *sendbuf, int sendcounts[], int sdispls[],
31
                     MPI_Datatype sendtypes[], void *recvbuf, int recvcounts[],
32
                     int rdispls[], MPI_Datatype recvtypes[], MPI_Comm comm)
33
     MPI_ALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF, RECVCOUNTS,
34
                     RDISPLS, RECVTYPES, COMM, IERROR)
35
          <type> SENDBUF(*), RECVBUF(*)
36
          INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPES(*), RECVCOUNTS(*),
37
          RDISPLS(*), RECVTYPES(*), COMM, IERROR
38
39
     void MPI::Comm::Alltoallw(const void* sendbuf, const int sendcounts[],
40
                     const int sdispls[], const MPI::Datatype sendtypes[], void*
41
                     recvbuf, const int recvcounts[], const int rdispls[], const
42
                     MPI::Datatype recvtypes[]) const = 0
43
          MPI_ALLTOALLW is the most general form of All-to-all. Like
44
     MPI_TYPE_CREATE_STRUCT, the most general type constructor, MPI_ALLTOALLW al-
45
     lows separate specification of count, displacement and datatype. In addition, to allow max-
46
     imum flexibility, the displacement of blocks within the send and receive buffers is specified
47
     in bytes.
```

If comm is an intracommunicator, then the j-th block sent from process i is received by process j and is placed in the i-th block of recvbuf. These blocks need not all have the same size.

The type signature associated with sendcounts[j], sendtypes[j] at process i must be equal to the type signature associated with recvcounts[i], recvtypes[i] at process j. This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. Distinct type maps between sender and receiver are still allowed.

The outcome is as if each process sent a message to every other process with

```
MPI_Send(sendbuf + sdispls[i], sendcounts[i], sendtypes[i], i, ...),
```

and received a message from every other process with a call to

```
MPI_Recv(recvbuf + rdispls[i], recvcounts[i], recvtypes[i], i, ...).
```

All arguments on all processes are significant. The argument comm must describe the same communicator on all processes.

No "in place" option is supported.

If comm is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The j-th send buffer of process i in group A should be consistent with the i-th receive buffer of process j in group B, and vice versa.

Rationale. The MPI\_ALLTOALLW function generalizes several MPI functions by carefully selecting the input arguments. For example, by making all but one process have sendcounts[i] = 0, this achieves an MPI\_SCATTERW function. (End of rationale.)

### 5.9 Global Reduction Operations

The functions in this section perform a global reduce operation (such as sum, max, logical AND, etc.) across all members of a group. The reduction operation can be either one of a predefined list of operations, or a user-defined operation. The global reduction functions come in several flavors: a reduce that returns the result of the reduction to one member of a group, an all-reduce that returns this result to all members of a group, and two scan (parallel prefix) operations. In addition, a reduce-scatter operation combines the functionality of a reduce and of a scatter operation.

#### 5.9.1 Reduce

```
MPI_REDUCE( sendbuf, recvbuf, count, datatype, op, root, comm)
```

```
sendbuf
IN
                                           address of send buffer (choice)
OUT
           recvbuf
                                           address of receive buffer (choice, significant only at
IN
           count
                                           number of elements in send buffer (non-negative inte-
                                           ger)
IN
           datatype
                                           data type of elements of send buffer (handle)
IN
                                           reduce operation (handle)
           op
                                           rank of root process (integer)
IN
           root
IN
           comm
                                           communicator (handle)
```

If comm is an intracommunicator, MPI\_REDUCE combines the elements provided in the input buffer of each process in the group, using the operation op, and returns the combined value in the output buffer of the process with rank root. The input buffer is defined by the arguments sendbuf, count and datatype; the output buffer is defined by the arguments recvbuf, count and datatype; both have the same number of elements, with the same type. The routine is called by all group members using the same arguments for count, datatype, op, root and comm. Thus, all processes provide input buffers and output buffers of the same length, with elements of the same type. Each process can provide one element, or a sequence of elements, in which case the combine operation is executed element-wise on each entry of the sequence. For example, if the operation is MPI\_MAX and the send buffer contains two elements that are floating point numbers (count = 2 and datatype = MPI\_FLOAT), then recvbuf(1) = global max(sendbuf(1)) and recvbuf(2) = global max(sendbuf(2)).

Section 5.9.2, lists the set of predefined operations provided by MPI. That section also enumerates the datatypes each operation can be applied to. In addition, users may define their own operations that can be overloaded to operate on several datatypes, either basic or derived. This is further explained in Section 5.9.5.

The operation op is always assumed to be associative. All predefined operations are also assumed to be commutative. Users may define operations that are assumed to be associative, but not commutative. The "canonical" evaluation order of a reduction is determined by the ranks of the processes in the group. However, the implementation can take advantage of associativity, or associativity and commutativity in order to change the order of evaluation.

This may change the result of the reduction for operations that are not strictly associative and commutative, such as floating point addition.

Advice to implementors. It is strongly recommended that MPI\_REDUCE be implemented so that the same result be obtained whenever the function is applied on the same arguments, appearing in the same order. Note that this may prevent optimizations that take advantage of the physical location of processors. (End of advice to implementors.)

The datatype argument of MPI\_REDUCE must be compatible with op. Predefined operators work only with the MPI types listed in Section 5.9.2 and Section 5.9.4. Furthermore, the datatype and op given for predefined operators must be the same on all processes.

Note that it is possible for users to supply different user-defined operations to MPI\_REDUCE in each process. MPI does not define which operations are used on which operands in this case. User-defined operators may operate on general, derived datatypes. In this case, each argument that the reduce operation is applied to is one element described by such a datatype, which may contain several basic values. This is further explained in Section 5.9.5.

Advice to users. Users should make no assumptions about how MPI\_REDUCE is implemented. Safest is to ensure that the same function is passed to MPI\_REDUCE by each process. (End of advice to users.)

Overlapping datatypes are permitted in "send" buffers. Overlapping datatypes in "receive" buffers are erroneous and may give unpredictable results.

The "in place" option for intracommunicators is specified by passing the value MPI\_IN\_PLACE to the argument sendbuf at the root. In such case, the input data is taken at the root from the receive buffer, where it will be replaced by the output data.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Only send buffer arguments are significant in group B and only receive buffer arguments are significant at the root.

#### 5.9.2 Predefined Reduction Operations

The following predefined operations are supplied for MPI\_REDUCE and related functions MPI\_ALLREDUCE, MPI\_REDUCE\_SCATTER, MPI\_SCAN, and MPI\_EXSCAN. These operations are invoked by placing the following in op.

Name	Meaning
MPI_MAX	maximum
MPI_MIN	minimum
MPI_SUM	$\operatorname{sum}$
MPI_PROD	$\operatorname{product}$
MPI_LAND	logical and
MPI_BAND	bit-wise and

```
1
       MPI_LOR
                                               logical or
2
                                               bit-wise or
       MPI_BOR
                                               logical exclusive or (xor)
3
       MPI_LXOR
                                               bit-wise exclusive or (xor)
4
       MPI_BXOR
       MPI_MAXLOC
                                               max value and location
5
       MPI_MINLOC
                                               min value and location
6
         The two operations MPI_MINLOC and MPI_MAXLOC are discussed separately in Sec-
     tion 5.9.4. For the other predefined operations, we enumerate below the allowed combi-
9
     nations of op and datatype arguments. First, define groups of MPI basic datatypes in the
10
     following way.
11
12
13
       C integer:
                                               MPI_INT, MPI_LONG, MPI_SHORT,
14
                                               MPI_UNSIGNED_SHORT, MPI_UNSIGNED,
15
                                               MPI_UNSIGNED_LONG,
16
                                               MPI_LONG_LONG_INT,
17
                                               MPI_LONG_LONG (as synonym),
                                               MPI_UNSIGNED_LONG_LONG,
18
                                               MPI_SIGNED_CHAR, MPI_UNSIGNED_CHAR
19
       Fortran integer:
                                               MPI_INTEGER
                                               MPI_FLOAT, MPI_DOUBLE, MPI_REAL,
21
       Floating point:
                                               MPI_DOUBLE_PRECISION
22
                                               MPI_LONG_DOUBLE
23
       Logical:
                                               MPI_LOGICAL
24
                                               MPI_COMPLEX
       Complex:
25
                                               MPI_BYTE
       Byte:
26
27
         Now, the valid datatypes for each option is specified below.
28
29
                                               Allowed Types
30
       Op
31
       MPI_MAX, MPI_MIN
                                               C integer, Fortran integer, Floating point
       MPI_SUM, MPI_PROD
                                               C integer, Fortran integer, Floating point, Complex
33
       MPI_LAND, MPI_LOR, MPI_LXOR
                                               C integer, Logical
34
       MPI_BAND, MPI_BOR, MPI_BXOR
                                               C integer, Fortran integer, Byte
35
36
         The following examples use intracommunicators.
37
     Example 5.15 A routine that computes the dot product of two vectors that are distributed
39
     across a group of processes and returns the answer at node zero.
40
41
     SUBROUTINE PAR_BLAS1(m, a, b, c, comm)
42
     REAL a(m), b(m)
                              ! local slice of array
43
     REAL c
                              ! result (at node zero)
44
     REAL sum
45
     INTEGER m, comm, i, ierr
46
47
     ! local sum
     sum = 0.0
```

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42

44

45 46 47

```
DO i = 1, m
    sum = sum + a(i)*b(i)
END DO

! global sum
CALL MPI_REDUCE(sum, c, 1, MPI_REAL, MPI_SUM, 0, comm, ierr)
RETURN
```

**Example 5.16** A routine that computes the product of a vector and an array that are distributed across a group of processes and returns the answer at node zero.

```
SUBROUTINE PAR_BLAS2(m, n, a, b, c, comm)
REAL a(m), b(m,n)
                     ! local slice of array
REAL c(n)
                     ! result
REAL sum(n)
INTEGER n, comm, i, j, ierr
! local sum
DO j=1, n
  sum(j) = 0.0
 DO i = 1, m
    sum(j) = sum(j) + a(i)*b(i,j)
  END DO
END DO
! global sum
CALL MPI_REDUCE(sum, c, n, MPI_REAL, MPI_SUM, 0, comm, ierr)
! return result at node zero (and garbage at the other nodes)
RETURN
```

#### 5.9.3 Signed Characters and Reductions

The types MPI\_SIGNED\_CHAR and MPI\_UNSIGNED\_CHAR can be used in reduction operations. MPI\_CHAR (which represents printable characters) cannot be used in reduction operations. In a heterogeneous environment, MPI\_CHAR and MPI\_WCHAR will be translated so as to preserve the printable character, whereas MPI\_SIGNED\_CHAR and MPI\_UNSIGNED\_CHAR will be translated so as to preserve the integer value.

Advice to users. The types MPI\_CHAR and MPI\_CHARACTER are intended for characters, and so will be translated to preserve the printable representation, rather than the integer value, if sent between machines with different character codes. The types MPI\_SIGNED\_CHAR and MPI\_UNSIGNED\_CHAR should be used in C if the integer value should be preserved. (*End of advice to users*.)

#### 5.9.4 MINLOC and MAXLOC

The operator MPI\_MINLOC is used to compute a global minimum and also an index attached to the minimum value. MPI\_MAXLOC similarly computes a global maximum and index. One application of these is to compute a global minimum (maximum) and the rank of the process containing this value.

The operation that defines MPI\_MAXLOC is:

$$\left(\begin{array}{c} u\\i \end{array}\right) \circ \left(\begin{array}{c} v\\j \end{array}\right) = \left(\begin{array}{c} w\\k \end{array}\right)$$

where

$$w = \max(u, v)$$

and

$$k = \begin{cases} i & \text{if } u > v \\ \min(i, j) & \text{if } u = v \\ j & \text{if } u < v \end{cases}$$

MPI\_MINLOC is defined similarly:

$$\left(\begin{array}{c} u\\i \end{array}\right) \circ \left(\begin{array}{c} v\\j \end{array}\right) = \left(\begin{array}{c} w\\k \end{array}\right)$$

where

$$w = \min(u, v)$$

and

$$k = \begin{cases} i & \text{if } u < v \\ \min(i, j) & \text{if } u = v \\ j & \text{if } u > v \end{cases}$$

Both operations are associative and commutative. Note that if MPI\_MAXLOC is applied to reduce a sequence of pairs  $(u_0,0),(u_1,1),\ldots,(u_{n-1},n-1)$ , then the value returned is (u,r), where  $u=\max_i u_i$  and r is the index of the first global maximum in the sequence. Thus, if each process supplies a value and its rank within the group, then a reduce operation with  $\mathsf{op} = \mathsf{MPI\_MAXLOC}$  will return the maximum value and the rank of the first process with that value. Similarly, MPI\_MINLOC can be used to return a minimum and its index. More generally, MPI\_MINLOC computes a lexicographic minimum, where elements are ordered according to the first component of each pair, and ties are resolved according to the second component.

The reduce operation is defined to operate on arguments that consist of a pair: value and index. For both Fortran and C, types are provided to describe the pair. The potentially mixed-type nature of such arguments is a problem in Fortran. The problem is circumvented, for Fortran, by having the MPI-provided type consist of a pair of the same type as value, and coercing the index to this type also. In C, the MPI-provided pair type has distinct types and the index is an int.

In order to use MPI\_MINLOC and MPI\_MAXLOC in a reduce operation, one must provide a datatype argument that represents a pair (value and index). MPI provides nine such

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```
predefined data
types. The operations \mathsf{MPI\_MAXLOC} and \mathsf{MPI\_MINLOC} 
can be used with each of the following data
types.
```

```
Fortran:

Name

Description

pair of REALs

MPI_2DOUBLE_PRECISION

pair of DOUBLE PRECISION variables

MPI_2INTEGER

pair of INTEGERs
```

```
C:
Name Description
MPI_FLOAT_INT float and int
MPI_DOUBLE_INT double and int
MPI_LONG_INT long and int
MPI_2INT pair of int
MPI_SHORT_INT short and int
MPI_LONG_DOUBLE_INT long double and int
```

The datatype MPI\_2REAL is as if defined by the following (see Section ??).

```
MPI_TYPE_CONTIGUOUS(2, MPI_REAL, MPI_2REAL)
```

Similar statements apply for MPI\_2INTEGER, MPI\_2DOUBLE\_PRECISION, and MPI\_2INT. The datatype MPI\_FLOAT\_INT is *as if* defined by the following sequence of instructions.

```
type[0] = MPI_FLOAT
type[1] = MPI_INT
disp[0] = 0
disp[1] = sizeof(float)
block[0] = 1
block[1] = 1
MPI_TYPE_STRUCT(2, block, disp, type, MPI_FLOAT_INT)
```

Similar statements apply for MPI\_LONG\_INT and MPI\_DOUBLE\_INT.

The following examples use intracommunicators.

**Example 5.17** Each process has an array of 30 doubles, in C. For each of the 30 locations, compute the value and rank of the process containing the largest value.

```
39
                                                                                  40
/* each process has an array of 30 double: ain[30]
                                                                                  41
                                                                                   42
double ain[30], aout[30];
int ind[30];
                                                                                   44
struct {
                                                                                  45
    double val;
                                                                                  46
    int
          rank;
                                                                                   47
} in[30], out[30];
int i, myrank, root;
```

48

```
1
2
         MPI_Comm_rank(comm, &myrank);
3
         for (i=0; i<30; ++i) {
4
             in[i].val = ain[i];
5
             in[i].rank = myrank;
6
         MPI_Reduce( in, out, 30, MPI_DOUBLE_INT, MPI_MAXLOC, root, comm );
         /* At this point, the answer resides on process root
9
          */
10
         if (myrank == root) {
11
             /* read ranks out
12
              */
13
             for (i=0; i<30; ++i) {
                  aout[i] = out[i].val;
15
                  ind[i] = out[i].rank;
16
             }
17
         }
18
19
     Example 5.18 Same example, in Fortran.
20
21
22
         ! each process has an array of 30 double: ain(30)
23
24
         DOUBLE PRECISION ain(30), aout(30)
25
         INTEGER ind(30)
         DOUBLE PRECISION in(2,30), out(2,30)
27
         INTEGER i, myrank, root, ierr
28
29
         CALL MPI_COMM_RANK(comm, myrank, ierr)
30
         DO I=1, 30
             in(1,i) = ain(i)
             in(2,i) = myrank
                                   ! myrank is coerced to a double
33
         END DO
34
35
         CALL MPI_REDUCE( in, out, 30, MPI_2DOUBLE_PRECISION, MPI_MAXLOC, root,
                                                                        comm, ierr )
37
         ! At this point, the answer resides on process root
39
         IF (myrank .EQ. root) THEN
40
              ! read ranks out
41
             DO I = 1, 30
42
                  aout(i) = out(1,i)
                  ind(i) = out(2,i) ! rank is coerced back to an integer
44
             END DO
45
         END IF
46
```

**Example 5.19** Each process has a non-empty array of values. Find the minimum global value, the rank of the process that holds it and its index on this process.

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```
#define LEN
               1000
float val[LEN];
                       /* local array of values */
int count;
                       /* local number of values */
int myrank, minrank, minindex;
float minval;
struct {
    float value;
    int
          index;
} in, out;
    /* local minloc */
in.value = val[0];
in.index = 0;
for (i=1; i < count; i++)</pre>
    if (in.value > val[i]) {
        in.value = val[i];
        in.index = i;
    }
    /* global minloc */
MPI_Comm_rank(comm, &myrank);
in.index = myrank*LEN + in.index;
MPI_Reduce( in, out, 1, MPI_FLOAT_INT, MPI_MINLOC, root, comm );
    /* At this point, the answer resides on process root
     */
if (myrank == root) {
    /* read answer out
     */
    minval = out.value;
    minrank = out.index / LEN;
    minindex = out.index % LEN;
}
```

Rationale. The definition of MPI\_MINLOC and MPI\_MAXLOC given here has the advantage that it does not require any special-case handling of these two operations: they are handled like any other reduce operation. A programmer can provide his or her own definition of MPI\_MAXLOC and MPI\_MINLOC, if so desired. The disadvantage is that values and indices have to be first interleaved, and that indices and values have to be coerced to the same type, in Fortran. (End of rationale.)

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# 5.9.5 User-Defined Reduction Operations

```
MPI_OP_CREATE(function, commute, op)
```

```
IN function user defined function (function)
IN commute true if commutative; false otherwise.
OUT op operation (handle)
```

void MPI::Op::Init(MPI::User\_function\* function, bool commute)

MPI\_OP\_CREATE binds a user-defined global operation to an op handle that can subsequently be used in MPI\_REDUCE, MPI\_ALLREDUCE, MPI\_REDUCE\_SCATTER, MPI\_SCAN, and MPI\_EXSCAN. The user-defined operation is assumed to be associative. If commute = true, then the operation should be both commutative and associative. If commute = false, then the order of operands is fixed and is defined to be in ascending, process rank order, beginning with process zero. The order of evaluation can be changed, talking advantage of the associativity of the operation. If commute = true then the order of evaluation can be changed, taking advantage of commutativity and associativity.

function is the user-defined function, which must have the following four arguments: invec, inoutvec, len and datatype.

```
The ISO C prototype for the function is the following.

typedef void MPI_User_function(void *invec, void *inoutvec, int *len,

MPI_Datatype *datatype);
```

The Fortran declaration of the user-defined function appears below.

SUBROUTINE USER\_FUNCTION(INVEC, INOUTVEC, LEN, TYPE)

<type> INVEC(LEN), INOUTVEC(LEN)

INTEGER LEN, TYPE

The datatype argument is a handle to the data type that was passed into the call to MPI\_REDUCE. The user reduce function should be written such that the following holds: Let u[0], ..., u[len-1] be the len elements in the communication buffer described by the arguments invec, len and datatype when the function is invoked; let v[0], ..., v[len-1] be len elements in the communication buffer described by the arguments inoutvec, len and datatype when the function is invoked; let w[0], ..., w[len-1] be len elements in the communication buffer described by the arguments inoutvec, len and datatype when the function returns; then w[i] = u[i] \circ v[i], for i=0, ..., len-1, where  $\circ$  is the reduce operation that the function computes.

Informally, we can think of invec and inoutvec as arrays of len elements that function is combining. The result of the reduction over-writes values in inoutvec, hence the name. Each invocation of the function results in the pointwise evaluation of the reduce operator on len elements: I.e, the function returns in inoutvec[i] the value invec[i]  $\circ$  inoutvec[i], for  $i = 0, \ldots, count - 1$ , where  $\circ$  is the combining operation computed by the function.

Rationale. The len argument allows MPI\_REDUCE to avoid calling the function for each element in the input buffer. Rather, the system can choose to apply the function to chunks of input. In C, it is passed in as a reference for reasons of compatibility with Fortran.

By internally comparing the value of the datatype argument to known, global handles, it is possible to overload the use of a single user-defined function for several, different data types. (*End of rationale.*)

General datatypes may be passed to the user function. However, use of datatypes that are not contiguous is likely to lead to inefficiencies.

No MPI communication function may be called inside the user function. MPI\_ABORT may be called inside the function in case of an error.

Advice to users. Suppose one defines a library of user-defined reduce functions that are overloaded: the datatype argument is used to select the right execution path at each invocation, according to the types of the operands. The user-defined reduce function cannot "decode" the datatype argument that it is passed, and cannot identify, by itself, the correspondence between the datatype handles and the datatype they represent. This correspondence was established when the datatypes were created. Before the library is used, a library initialization preamble must be executed. This preamble code will define the datatypes that are used by the library, and store handles to these datatypes in global, static variables that are shared by the user code and the library code.

The Fortran version of MPI\_REDUCE will invoke a user-defined reduce function using the Fortran calling conventions and will pass a Fortran-type datatype argument; the C version will use C calling convention and the C representation of a datatype handle. Users who plan to mix languages should define their reduction functions accordingly. (End of advice to users.)

Advice to implementors. We outline below a naive and inefficient implementation of MPI\_REDUCE not supporting the "in place" option.

```
39
MPI_Comm_size(comm, &groupsize);
                                                                        40
MPI_Comm_rank(comm, &rank);
                                                                        41
if (rank > 0) {
                                                                        42
    MPI_Recv(tempbuf, count, datatype, rank-1,...);
    User_reduce(tempbuf, sendbuf, count, datatype);
                                                                        44
}
                                                                        45
if (rank < groupsize-1) {</pre>
                                                                        46
    MPI_Send(sendbuf, count, datatype, rank+1, ...);
}
/* answer now resides in process groupsize-1 \dots now send to root ^{48}
```

```
1
                    */
2
                  if (rank == root) {
3
                       MPI_Irecv(recvbuf, count, datatype, groupsize-1,..., &req);
4
                  }
5
                  if (rank == groupsize-1) {
6
                       MPI_Send(sendbuf, count, datatype, root, ...);
                  }
                  if (rank == root) {
9
                       MPI_Wait(&req, &status);
10
                  }
```

The reduction computation proceeds, sequentially, from process 0 to process groupsize-1. This order is chosen so as to respect the order of a possibly non-commutative operator defined by the function User\_reduce(). A more efficient implementation is achieved by taking advantage of associativity and using a logarithmic tree reduction. Commutativity can be used to advantage, for those cases in which the commute argument to MPI\_OP\_CREATE is true. Also, the amount of temporary buffer required can be reduced, and communication can be pipelined with computation, by transferring and reducing the elements in chunks of size len <count.

The predefined reduce operations can be implemented as a library of user-defined operations. However, better performance might be achieved if MPI\_REDUCE handles these functions as a special case. (*End of advice to implementors.*)

Marks a user-defined reduction operation for deallocation and sets op to MPI\_OP\_NULL.

#### Example of User-defined Reduce

It is time for an example of user-defined reduction. The example in this section uses an intracommunicator.

**Example 5.20** Compute the product of an array of complex numbers, in C.

```
typedef struct {
    double real,imag;
} Complex;

/* the user-defined function
```

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```
*/
void myProd( Complex *in, Complex *inout, int *len, MPI_Datatype *dptr )
    int i;
    Complex c;
    for (i=0; i< *len; ++i) {
        c.real = inout->real*in->real -
                   inout->imag*in->imag;
        c.imag = inout->real*in->imag +
                   inout->imag*in->real;
        *inout = c;
        in++; inout++;
    }
}
/* and, to call it...
 */
. . .
    /* each process has an array of 100 Complexes
    Complex a[100], answer[100];
    MPI_Op myOp;
    MPI_Datatype ctype;
    /* explain to MPI how type Complex is defined
    MPI_Type_contiguous( 2, MPI_DOUBLE, &ctype );
    MPI_Type_commit( &ctype );
    /* create the complex-product user-op
     */
    MPI_Op_create( myProd, True, &myOp );
    MPI_Reduce( a, answer, 100, ctype, myOp, root, comm );
    /* At this point, the answer, which consists of 100 Complexes,
     * resides on process root
     */
```

# 5.9.6 All-Reduce

MPI includes a variant of the reduce operations where the result is returned to all processes in a group. MPI requires that all processes from the same group participating in these operations receive identical results.

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```
1
     MPI_ALLREDUCE( sendbuf, recvbuf, count, datatype, op, comm)
2
       IN
                 sendbuf
                                             starting address of send buffer (choice)
3
       OUT
                 recvbuf
                                             starting address of receive buffer (choice)
4
5
       IN
                                             number of elements in send buffer (non-negative inte-
                 count
6
                                             ger)
       IN
                 datatype
                                             data type of elements of send buffer (handle)
       IN
                 ор
                                             operation (handle)
9
10
       IN
                 comm
                                             communicator (handle)
11
12
     int MPI_Allreduce(void* sendbuf, void* recvbuf, int count,
13
                     MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
14
     MPI_ALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
15
          <type> SENDBUF(*), RECVBUF(*)
16
          INTEGER COUNT, DATATYPE, OP, COMM, IERROR
17
18
     void MPI::Comm::Allreduce(const void* sendbuf, void* recvbuf, int count,
19
                     const MPI::Datatype& datatype, const MPI::Op& op) const = 0
20
         If comm is an intracommunicator, MPI_ALLREDUCE behaves the same as
21
     MPI_REDUCE except that the result appears in the receive buffer of all the group members.
22
23
                                      The all-reduce operations can be implemented as a re-
           Advice to implementors.
24
25
```

duce, followed by a broadcast. However, a direct implementation can lead to better performance. (End of advice to implementors.)

The "in place" option for intracommunicators is specified by passing the value MPI\_IN\_PLACE to the argument sendbuf at all processes. In this case, the input data is taken at each process from the receive buffer, where it will be replaced by the output data.

If comm is an intercommunicator, then the result of the reduction of the data provided by processes in group A is stored at each process in group B, and vice versa. Both groups should provide count and datatype arguments that specify the same type signature.

The following example uses an intracommunicator.

**Example 5.21** A routine that computes the product of a vector and an array that are distributed across a group of processes and returns the answer at all nodes (see also Example 5.16).

```
SUBROUTINE PAR_BLAS2(m, n, a, b, c, comm)
40
     REAL a(m), b(m,n)
                           ! local slice of array
     REAL c(n)
                           ! result
42
     REAL sum(n)
43
     INTEGER n, comm, i, j, ierr
45
     ! local sum
46
     DO j = 1, n
       sum(j) = 0.0
       D0 i = 1, m
```

```
sum(j) = sum(j) + a(i)*b(i,j)
END DO
END DO
! global sum
CALL MPI_ALLREDUCE(sum, c, n, MPI_REAL, MPI_SUM, comm, ierr)
! return result at all nodes
RETURN
```

# 5.10 Reduce-Scatter

MPI includes a variant of the reduce operations where the result is scattered to all processes in a group on return.

MPI\_REDUCE\_SCATTER( sendbuf, recvbuf, recvcounts, datatype, op, comm)

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	recvcounts	non-negative integer array specifying the number of elements in result distributed to each process. Array must be identical on all calling processes.
IN	datatype	data type of elements of input buffer (handle)
IN	ор	operation (handle)
IN	comm	communicator (handle)

```
<type> SENDBUF(*), RECVBUF(*)
INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, IERROR
```

If comm is an intracommunicator, MPI\_REDUCE\_SCATTER first does an element-wise reduction on vector of count =  $\sum_i$  recvcounts[i] elements in the send buffer defined by sendbuf, count and datatype. Next, the resulting vector of results is split into n disjoint segments, where n is the number of members in the group. Segment i contains recvcounts[i] elements. The i-th segment is sent to process i and stored in the receive buffer defined by recvbuf, recvcounts[i] and datatype.

Advice to implementors. The MPI\_REDUCE\_SCATTER routine is functionally equivalent to: an MPI\_REDUCE collective operation with count equal to the sum of

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recvcounts[i] followed by MPI\_SCATTERV with sendcounts equal to recvcounts. However, a direct implementation may run faster. (*End of advice to implementors*.)

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE in the sendbuf argument. In this case, the input data is taken from the top of the receive buffer.

If comm is an intercommunicator, then the result of the reduction of the data provided by processes in group A is scattered among processes in group B, and vice versa. Within each group, all processes provide the same recvcounts argument, and the sum of the recvcounts entries should be the same for the two groups.

Rationale. The last restriction is needed so that the length of the send buffer can be determined by the sum of the local recvcounts entries. Otherwise, a communication is needed to figure out how many elements are reduced. (*End of rationale*.)

# 5.11 Scan

#### 5.11.1 Inclusive Scan

MPI\_SCAN( sendbuf, recvbuf, count, datatype, op, comm )

```
IN
           sendbuf
                                           starting address of send buffer (choice)
OUT
           recvbuf
                                           starting address of receive buffer (choice)
IN
                                           number of elements in input buffer (non-negative in-
           count
                                           teger)
IN
           datatype
                                           data type of elements of input buffer (handle)
IN
                                           operation (handle)
           op
IN
           comm
                                           communicator (handle)
```

```
MPI_SCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
   INTEGER COUNT, DATATYPE, OP, COMM, IERROR
```

If comm is an intracommunicator, MPI\_SCAN is used to perform a prefix reduction on data distributed across the group. The operation returns, in the receive buffer of the process with rank i, the reduction of the values in the send buffers of processes with ranks 0,...,i (inclusive). The type of operations supported, their semantics, and the constraints on send and receive buffers are as for MPI\_REDUCE.

The "in place" option for intracommunicators is specified by passing MPI\_IN\_PLACE in the sendbuf argument. In this case, the input data is taken from the receive buffer, and replaced by the output data.

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This operation is invalid for intercommunicators.

#### 5.11.2 Exclusive Scan

# MPI\_EXSCAN(sendbuf, recvbuf, count, datatype, op, comm)

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	count	number of elements in input buffer (non-negative integer)
IN	datatype	data type of elements of input buffer (handle)
IN	ор	operation (handle)
IN	comm	intracommunicator (handle)

If comm is an intracommunicator, MPI\_EXSCAN is used to perform a prefix reduction on data distributed across the group. The value in recvbuf on the process with rank 0 is undefined, and recvbuf is not significant on process 0. The value in recvbuf on the process with rank 1 is defined as the value in sendbuf on the process with rank 0. For processes with rank i > 1, the operation returns, in the receive buffer of the process with rank i, the reduction of the values in the send buffers of processes with ranks  $0, \ldots, i-1$  (inclusive). The type of operations supported, their semantics, and the constraints on send and receive buffers, are as for MPI\_REDUCE.

No "in place" option is supported.

This operation is invalid for intercommunicators.

Advice to users. As for MPI\_SCAN, MPI does not specify which processes may call the operation, only that the result be correctly computed. In particular, note that the process with rank 1 need not call the MPI\_Op, since all it needs to do is to receive the value from the process with rank 0. However, all processes, even the processes with ranks zero and one, must provide the same op. (End of advice to users.)

Rationale. The exclusive scan is more general than the inclusive scan. Any inclusive scan operation can be achieved by using the exclusive scan and then locally combining the local contribution. Note that for non-invertable operations such as MPI\_MAX, the exclusive scan cannot be computed with the inclusive scan.

No in-place version is specified for MPI\_EXSCAN because it is not clear what this means for the process with rank zero. (*End of rationale*.)

# 5.11.3 Example using MPI\_SCAN

The example in this section uses an intracommunicator.

**Example 5.22** This example uses a user-defined operation to produce a *segmented scan*. A segmented scan takes, as input, a set of values and a set of logicals, and the logicals delineate the various segments of the scan. For example:

The operator that produces this effect is,

$$\left(\begin{array}{c} u\\i\end{array}\right)\circ\left(\begin{array}{c} v\\j\end{array}\right)=\left(\begin{array}{c} w\\j\end{array}\right),$$

where,

$$w = \left\{ \begin{array}{ll} u + v & \text{if } i = j \\ v & \text{if } i \neq j \end{array} \right..$$

Note that this is a non-commutative operator. C code that implements it is given below.

```
22
     typedef struct {
23
          double val;
24
          int log;
25
     } SegScanPair;
26
27
     /* the user-defined function
28
29
     void segScan( SegScanPair *in, SegScanPair *inout, int *len,
30
                                                           MPI_Datatype *dptr )
31
     {
32
          int i;
33
          SegScanPair c;
34
35
         for (i=0; i< *len; ++i) {
36
              if ( in->log == inout->log )
37
                   c.val = in->val + inout->val;
              else
39
                   c.val = inout->val;
40
              c.log = inout->log;
41
              *inout = c;
42
              in++; inout++;
43
          }
44
     }
45
```

Note that the inout argument to the user-defined function corresponds to the right-hand operand of the operator. When using this operator, we must be careful to specify that it is non-commutative, as in the following.

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```
int i, base;
SeqScanPair
             a, answer;
MPI_Op
             myOp;
MPI_Datatype type[2] = {MPI_DOUBLE, MPI_INT};
MPI\_Aint
             disp[2];
             blocklen[2] = \{ 1, 1 \};
int
MPI_Datatype sspair;
/* explain to MPI how type SegScanPair is defined
 */
MPI_Address( a, disp);
MPI_Address( a.log, disp+1);
base = disp[0];
for (i=0; i<2; ++i) disp[i] -= base;
MPI_Type_struct( 2, blocklen, disp, type, &sspair );
MPI_Type_commit( &sspair );
/* create the segmented-scan user-op
 */
MPI_Op_create( segScan, 0, &myOp );
MPI_Scan( a, answer, 1, sspair, myOp, comm );
```

# 5.12 Nonblocking Collective Operations

As described in Chapter ??, the performance of many systems can be improved by overlapping communication and computation. Nonblocking collective operations combine the potential to utilize overlap and avoid synchronization of nonblocking point-to-point operations with the optimized implementation and message scheduling of collective operations [2, 5]. One way of doing this would be to perform the collective operation in a separate thread. An alternative mechanism that often leads to better performance (i.e, avoids context switching and scheduler overheads and thread management [3]) is the use of nonblocking collective communication. The model is similar to point-to-point communications ??. A nonblocking start call is used to initiate a collective communication which is eventually completed by a separate call. As in the nonblocking point-to-point case, the communication may progress independently of the computations at all participating processes. Nonblocking collective communication can also be used to mitigate synchronizing effects of collective operations by running them in the "background".

As in the point-to-point case, all start calls are local and return immediately with a handle to the operation, irrespective of the status of other processes. Multiple nonblocking collective communications can be outstanding on a single communicator. If the call causes some system resource to be exhausted, then it will fail and return an error code. Quality implementations of MPI should ensure that this happens only in "pathological" cases. That is, an MPI implementation should be able to support a large number of pending nonblocking operations.

A nonblocking collective call indicates that the system may start copying data out of the send buffer and into the receive buffer. All associated buffers should not be accessed between the initiation and the completion of a nonblocking collective operation. Collective operations

complete locally when the local part of the operation has been performed (i.e., the semantics of the collective operation are guaranteed) and all buffers can be accessed. Similarly to the blocking case, completion does not imply that other processes have completed or even started the operation. However, calling blocking completion functions (e.g., MPI\_WAIT) may synchronize the calling processes.

Advice to implementors. The nonblocking interface allows the user to specify overlapping communication and computation. High-quality MPI implementations should support the user by asynchronously progressing outstanding communications. (End of advice to implementors.)

All request test and wait functions (MPI\_{WAIT,TEST}\_{,ANY,SOME,ALL}) described in Section ?? are supported for nonblocking collective communications. MPI\_REQUEST\_FREE is not supported.

Rationale. After an active receive request was freed, there is no way to verify that the operation is completed and the receive buffer can be used ??. Collective communications have send and receive semantics and thus, freeing a request is not useful. (End of rationale.)

MPI\_CANCEL is not supported. Collective operations do not have a tag argument.

Rationale. Not having tags for collective operations simplifies the implementation (especially for hardware-supported optimizations) and is consistent to blocking point-to-point operations. (End of rationale.)

Advice to implementors. Nonblocking collective operations can be implemented with local execution schedules [4] using normal point-to-point communication and a reserved tag-space. (End of advice to implementors.)

All processes must call collective operations (blocking and nonblocking) in the same order. In particular, if some process calls a collective operation, all other processes in the communicator must eventually call the *same* collective operation, and no other collective operation in between. This is consistent with the ordering rules for blocking collective operations in threaded environments. Progression rules for nonblocking collectives are similar to progression of nonblocking point-to-point operations, refer to ??.

Rationale. Matching blocking and nonblocking collectives is not allowed because the implementation might use different communication algorithms for the two cases. Blocking collectives only need to be optimized for their running time while nonblocking collectives have to find an equilibrium between time to completion, CPU overhead and asynchronous progression. (End of rationale.)

Advice to users. If blocking semantics are required on some processes of the communicator, then the user can use a nonblocking collective immediately followed by a call to wait in order to emulate blocking behavior. (End of advice to users.)

Status objects that are passed to MPI\_{WAIT,TEST}, ANY,SOME,ALL} will be ignored by the library (remain unchanged) if the request is associated to a nonblocking collective routine.

Advice to users. The user is encouraged to pass MPI\_STATUS{ES}\_IGNORE as status object to all requests of nonblocking collective routines. (End of advice to users.)

MPI::Request MPI::Comm::Ibarrier() const = 0

# 5.12.1 Nonblocking Barrier Synchronization

If comm is an intracommunicator, MPI\_IBARRIER does not complete until all group members have called it. The call completes at any process only after all group members have started the call.

If comm is an intercommunicator, the barrier is performed across all processes in the intercommunicator. In this case, all processes in one group (group A) of the intercommunicator may complete the barrier when all of the processes in the other group (group B) have started the barrier.

Advice to users. A nonblocking barrier can be used to hide latency. Moving independent computations between the MPI\_IBARRIER and the subsequent completion call can overlap the barrier latency and therefore shorten possible waiting times. The semantic properties are also useful when mixing collectives and point-to-point messages. (End of advice to users.)

#### 5.12.2 Nonblocking Broadcast

MPI\_IBCAST( buffer, count, datatype, root, comm, request )

INOUT	buffer	starting address of buffer (choice)
IN	count	number of entries in buffer (non-negative integer)
IN	datatype	data type of buffer (handle)
IN	root	rank of broadcast root (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

If comm is an intracommunicator, MPI\_IBCAST starts the broadcast of a message from the process with rank root to all processes of the group, itself included. It is called by all members of the group using the same arguments for comm and root. After completion, the content of root's buffer has been copied to all other processes.

If comm is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument root, which is the rank of the root in group A. The root passes the value MPI\_ROOT in root. All other processes in group A pass the value MPI\_PROC\_NULL in root. Data is broadcast from the root to all processes in group B. The buffer arguments of the processes in group B must be consistent with the buffer argument of the root.

# Example using MPI\_IBCAST

The example in this section uses intracommunicators.

**Example 5.23** Start a broadcast of 100 ints from process 0 to every process in the group, perform some computation on independent data, and then complete the outstanding broadcast operation.

```
MPI_Comm comm;
int array1[100], array2[100];
int root=0;
MPI_Request req;
...
MPI_Ibcast( array1, 100, MPI_INT, root, comm, &req );
compute(array2, 100);
MPI_Wait(&req, MPI_STATUS_IGNORE);
```

As in many of our example code fragments, we assume that some of the variables (such as comm in the above) have been assigned appropriate values.

# 5.12.3 Nonblocking Gather

MPI\_IGATHER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	recvcount	number of elements for any single receive (non-negative integer, significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_IGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST, IERROR

This operation starts a nonblocking gather. The data placements after the operation completes are identical as after a call to the blocking MPI\_GATHER.

MPI\_IGATHERV( sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs, recvtype, root, comm, request)

IN	sendbut	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at
		root)

1 2 3	IN	recvcounts	non-negative integer array (of length group size) containing the number of elements that are received from each process (significant only at root)
4 5 6 7 8	IN	displs	integer array (of length group size). Entry i specifies the displacement relative to recvbuf at which to place the incoming data from process i (significant only at root)
9	IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
11	IN	root	rank of receiving process (integer)
12	IN	comm	communicator (handle)
13 14	OUT	request	communication request (handle)
15		•	1 /
16	int MPI	_Igatherv(void* se	ndbuf, int sendcount, MPI_Datatype sendtype,
17		void* recvbu	uf, int *recvcounts, int *displs,
18		MPI_Datatype	e recvtype, int root, MPI_Comm comm,
19		${\tt MPI\_Request}$	*request)
20	MDT TCA	THERN/GENDRIE GEN	DCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
21	111 1_10A	=	DOGONI, BENDITTE, RECYDOI, RECYCOONIB, DIBLES,
22	<tv< td=""><td>pe&gt; SENDBUF(*), RE</td><td></td></tv<>	pe> SENDBUF(*), RE	
23	-	=	NDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT,
24		M, REQUEST, IERROR	
25 26	MDT D -	T	
27	MPI::Ke	_	gatherv(const void* sendbuf, int sendcount, const be& sendtype, void* recvbuf,
28		V -	ecvcounts[], const int displs[],
29			Datatype& recvtype, int root) const = 0
30	NAD		the functionality of MDLICATHED by allowing a verying

 $\mathsf{MPI\_IGATHERV}$  extends the functionality of  $\mathsf{MPI\_IGATHER}$  by allowing a varying count of data from each process. The memory movement after completion is identical as for  $\mathsf{MPI\_GATHERV}.$ 

# 5.12.4 Nonblocking Scatter

MPI\_ISCATTER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm, request)

IN	sendbuf	address of send buffer (choice, significant only at root)
IN	sendcount	number of elements sent to each process (non-negative integer, significant only at root) $$
IN	sendtype	data type of send buffer elements (significant only at root) (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements in receive buffer (non-negative integer) $$
IN	recvtype	data type of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_ISCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST, IERROR

MPI\_ISCATTER starts the reverse data movement as MPI\_IGATHER. The data movement performed is equivalent to MPI\_SCATTER.

MPI\_ISCATTERV( sendbuf, sendcounts, displs, sendtype, recvbuf, recvcount, recvtype, root, comm, request)

IN sendbuf address of send buffer (choice, significant only at root)

1 2	IN	sendcounts	non-negative integer array (of length group size) specifying the number of elements to send to each processor
3			
4	IN	displs	integer array (of length group size). Entry i specifies
5	114	aispis	the displacement (relative to sendbuf) from which to
6			take the outgoing data to process i
7 8	IN	sendtype	data type of send buffer elements (handle)
9	OUT	recvbuf	, , , , , , , , , , , , , , , , , , ,
10		recybui	address of receive buffer (choice)
11 12	IN	recvcount	number of elements in receive buffer (non-negative integer)
13	IN	recvtype	data type of receive buffer elements (handle)
14	IN	root	rank of sending process (integer)
15			
16	IN	comm	communicator (handle)
17	OUT	request	communication request (handle)
18			
19	int MPI_		ouf, int *sendcounts, int *displs,
20		· -	ndtype, void* recvbuf, int recvcount,
21		· -	cvtype, int root, MPI_Comm comm,
22		MPI_Request *re	quest)
23	MPI ISCA	TTERV(SENDBUF, SENDCO	DUNTS, DISPLS, SENDTYPE, RECVBUF, RECVCOUNT,
24	RECVTYPE, ROOT, COMM, REQUEST, IERROR)		
25	<pre><type> SENDBUF(*), RECVBUF(*)</type></pre>		
26	INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, RECVCOUNT, RECVTYPE, ROOT,		
27	COMM, REQUEST, IERROR		
28 29	MDT··Reg	uest MPT··Comm··Tscat	tterv(const void* sendbuf,
30	in iteq		ounts[], const int displs[],
31			type& sendtype, void* recvbuf, int recvcount,
32			type& recvtype, int root) const = 0
33	MDI		
34		SCALLERV starts the	reverse data movement as MPI_IGATHERV. The data

MPI\_ISCATTERV starts the reverse data movement as MPI\_IGATHERV. The data movement performed is equivalent to MPI\_SCATTERV.

# 5.12.5 Nonblocking Gather-to-all

MPI\_IALLGATHER( sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements received from any process (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_IALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, REQUEST, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, REQUEST, IERROR

The data movement after an  $\mathsf{MPI\_IALLGATHER}$  operation completes is identical to  $\mathsf{MPI\_ALLGATHER}$ .

MPI\_IALLGATHERV( sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs, recvtype, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)

1 2 3	IN	recvcounts	non-negative integer array (of length group size) containing the number of elements that are received from
			each process
4	IN	displs	integer array (of length group size). Entry i specifies
5		·	the displacement (relative to recvbuf) at which to place
6			the incoming data from process i
7	IN	rocutumo	
8	IIN	recvtype	data type of receive buffer elements (handle)
9	IN	comm	communicator (handle)
10	OUT	request	communication request (handle)
11		1,111	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
12	in+ MDT	Tallmathamu(waid*	gondbuf int gondcount MDT Datatune gondtune
13	int MPI_Iallgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype, void* recvbuf, int *recvcounts, int *displs,		
14			- · · · · · · · · · · · · · · · · · · ·
15		MP1_Datatype	recvtype, MPI_Comm comm, MPI_Request)
16	MPI_IAL	LGATHERV(SENDBUF, S	SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
17		RECVTYPE, CO	MM, REQUEST, IERROR)
18	<tv< td=""><td>rpe&gt; SENDBUF(*), REG</td><td></td></tv<>	rpe> SENDBUF(*), REG	
19	·	•	NDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, COMM,
20		UEST, IERROR	, , , , , , , , , , , , , , , , , , , ,
21			
22	MPI::Re	-	allgatherv(const void* sendbuf, int sendcount,
23			atatype& sendtype, void* recvbuf,
24			cvcounts[], const int displs[],
25		const MPI::D	atatype& recvtype) const = 0

The data movement after completion of  $\mathsf{MPI\_IALLGATHERV}$  is identical as if  $\mathsf{MPI\_ALLGATHERV}$  returned.

# 5.12.6 Nonblocking All-to-All Scatter/Gather

MPI\_IALLTOALL(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements sent to each process (non-negative integer) $$
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements received from any process (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_IALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, REQUEST, IERROR)

<type> SENDBUF(\*), RECVBUF(\*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, REQUEST, IERROR

The data movement after an  $\mathsf{MPI\_IALLTOALL}$  operation completes is identical to  $\mathsf{MPI\_ALLTOALL}$ .

MPI\_IALLTOALLV(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcounts, rdispls, recvtype, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcounts	non-negative integer array equal to the group size specifying the number of elements to send to each processor
IN	sdispls	integer array (of length group size). Entry j specifies the displacement (relative to sendbuf) from which to take the outgoing data destined for process j
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)

29

30

31

```
1
       IN
                 recvcounts
                                             non-negative integer array equal to the group size spec-
2
                                             ifying the number of elements that can be received
3
                                             from each processor
4
       IN
                 rdispls
                                             integer array (of length group size). Entry i specifies
5
                                             the displacement (relative to recvbuf) at which to place
6
                                             the incoming data from process i
       IN
                                             data type of receive buffer elements (handle)
                 recvtype
9
       IN
                                             communicator (handle)
                 comm
10
       OUT
                 request
                                             communication request (handle)
11
12
     int MPI_Ialltoallv(void* sendbuf, int *sendcounts, int *sdispls,
13
                    MPI_Datatype sendtype, void* recvbuf, int *recvcounts,
14
                    int *rdispls, MPI_Datatype recvtype, MPI_Comm comm,
15
                    MPI_Request *request)
16
17
     MPI_IALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, RECVCOUNTS,
18
                    RDISPLS, RECVTYPE, COMM, REQUEST, IERROR)
19
          <type> SENDBUF(*), RECVBUF(*)
20
          INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPE, RECVCOUNTS(*), RDISPLS(*),
21
         RECVTYPE, COMM, REQUEST, IERROR
22
     MPI::Request MPI::Comm::Ialltoallv(const void* sendbuf,
23
                    const int sendcounts[], const int sdispls[],
24
                    const MPI::Datatype& sendtype, void* recvbuf,
25
                    const int recvcounts[], const int rdispls[],
                    const MPI::Datatype& recvtype) const = 0
27
```

MPI\_IALLTOALLV adds flexibility to MPI\_IALLTOALL in that the location of data for the send is specified by sdispls and the location of the placement of the data on the receive side is specified by rdispls.

MPI\_IALLTOALLW(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcounts, rdispls, recvtypes, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcounts	integer array equal to the group size specifying the number of elements to send to each processor (array of non-negative integers)
IN	sdispls	integer array (of length group size). Entry j specifies the displacement in bytes (relative to sendbuf) from which to take the outgoing data destined for process j (array of integers)
IN	sendtypes	array of datatypes (of length group size). Entry j specifies the type of data to send to process j (array of handles)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcounts	integer array equal to the group size specifying the number of elements that can be received from each processor (array of non-negative integers)
IN	rdispls	integer array (of length group size). Entry i specifies the displacement in bytes (relative to recvbuf) at which to place the incoming data from process i (array of integers)
IN	recvtypes	array of datatypes (of length group size). Entry i specifies the type of data received from process i (array of handles)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_IALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF,
RECVCOUNTS, RDISPLS, RECVTYPES, REQUEST, COMM, IERROR)
<type> SENDBUF(\*), RECVBUF(\*)
INTEGER SENDCOUNTS(\*), SDISPLS(\*), SENDTYPES(\*), RECVCOUNTS(\*),
RDISPLS(\*), RECVTYPES(\*), COMM, REQUEST, IERROR

 $\mathsf{MPI\_IALLTOALLW}$  is the nonblocking variant of  $\mathsf{MPI\_ALLTOALLW}.$  It starts a non-blocking all-to-all operation which delivers the same results as  $\mathsf{MPI\_ALLTOALLW}$  after completion.

# 5.12.7 Nonblocking Reduce

```
MPI_IREDUCE( sendbuf, recvbuf, count, datatype, op, root, comm, request)
```

IN	sendbuf	address of send buffer (choice)
OUT	recvbuf	address of receive buffer (choice, significant only at $\operatorname{root}$ )
IN	count	number of elements in send buffer (non-negative integer) $$
IN	datatype	data type of elements of send buffer (handle)
IN	ор	reduce operation (handle)
IN	root	rank of root process (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

MPI\_IREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, COMM, REQUEST, IERROR)

```
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, ROOT, COMM, REQUEST, IERROR
```

MPI\_IREDUCE is the nonblocking variant of MPI\_REDUCE. It starts a nonblocking reduction operation which delivers the same results as MPI\_REDUCE after completion.

Advice to implementors. It is strongly recommended that MPI\_IREDUCE is implemented so that the same result is obtained whenever the function is applied on the same arguments, appearing in the same order. Note that this may prevent optimizations that take advantage of the physical location of processors. (End of advice to implementors.)

#### 5.12.8 Nonblocking All-Reduce

MPI includes a variant of the reduce operations where the result is returned to all processes in a group. MPI requires that all processes from the same group participating in these operations receive identical results.

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```
MPI_IALLREDUCE( sendbuf, recvbuf, count, datatype, op, comm, request)
 IN
           sendbuf
                                       starting address of send buffer (choice)
 OUT
           recvbuf
                                       starting address of receive buffer (choice)
                                       number of elements in send buffer (non-negative inte-
 IN
           count
                                       ger)
 IN
           datatype
                                       data type of elements of send buffer (handle)
 IN
           op
                                       operation (handle)
 IN
           comm
                                       communicator (handle)
 OUT
           request
                                       communication request (handle)
int MPI_Iallreduce(void* sendbuf, void* recvbuf, int count,
              MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
              MPI_Request *request)
MPI_IALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST,
               IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
MPI::Request MPI::Comm::Iallreduce(const void* sendbuf, void* recvbuf,
               int count, const MPI::Datatype& datatype, const MPI::Op& op)
               const = 0
    MPI_IALLREDUCE is the nonblocking variant of MPI_ALLREDUCE. It starts a non-
blocking reduction-to-all operation which delivers the same results as MPI_ALLREDUCE
after completion.
        Nonblocking Reduce-Scatter
5.12.9
MPI_IREDUCE_SCATTER( sendbuf, recvbuf, recvcounts, datatype, op, comm, request)
```

IN

OUT

comm

request

```
IN
           sendbuf
                                           starting address of send buffer (choice)
OUT
           recvbuf
                                           starting address of receive buffer (choice)
IN
                                           non-negative integer array specifying the number of
           recvcounts
                                           elements in result distributed to each process. Array
                                           must be identical on all calling processes.
IN
           datatype
                                           data type of elements of input buffer (handle)
IN
                                           operation (handle)
           op
```

communicator (handle)

communication request (handle)

```
int MPI_Ireduce_scatter(void* sendbuf, void* recvbuf, int *recvcounts,
             MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
             MPI_Request *request)
```

```
1
     MPI_IREDUCE_SCATTER(SENDBUF, RECVBUF, RECVCOUNTS, DATATYPE, OP, COMM,
2
                    REQUEST, IERROR)
3
          <type> SENDBUF(*), RECVBUF(*)
4
          INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, REQUEST, IERROR
5
     MPI::Request MPI::Comm::Ireduce_scatter(const void* sendbuf, void* recvbuf,
6
                    int recvcounts[], const MPI::Datatype& datatype,
                    const MPI::Op& op) const = 0
8
9
         MPI_IREDUCE_SCATTER is the nonblocking variant of MPI_REDUCE_SCATTER. It
10
     starts a nonblocking reduce-scatter operation which delivers the same results as
11
     MPI_REDUCE_SCATTER after completion.
12
13
              Nonblocking Inclusive Scan
     5.12.10
14
15
16
     MPI_ISCAN( sendbuf, recvbuf, count, datatype, op, comm, request )
17
       IN
                 sendbuf
                                            starting address of send buffer (choice)
18
19
       OUT
                 recvbuf
                                            starting address of receive buffer (choice)
       IN
                                            number of elements in input buffer (non-negative in-
                 count
21
22
       IN
                datatype
                                            data type of elements of input buffer (handle)
23
24
       IN
                                            operation (handle)
                op
25
                                            communicator (handle)
       IN
                 comm
       OUT
                 request
                                            communication request (handle)
27
28
     int MPI_Iscan(void* sendbuf, void* recvbuf, int count,
29
30
                    MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
31
                    MPI_Request *request )
32
     MPI_ISCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
33
          <type> SENDBUF(*), RECVBUF(*)
34
          INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
35
36
     MPI::Request MPI::Intracomm::Iscan(const void* sendbuf, void* recvbuf,
37
                    int count, const MPI::Datatype& datatype, const MPI::Op& op)
38
                    const
39
         MPI_ISCAN is the nonblocking variant of MPI_SCAN. It starts a nonblocking scan
40
     operation which delivers the same results as MPI_SCAN after completion.
41
42
```

5.12.11 Nonblocking Exclusive Scan

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```
MPI_IEXSCAN(sendbuf, recvbuf, count, datatype, op, comm, request)
 IN
           sendbuf
                                       starting address of send buffer (choice)
 OUT
           recvbuf
                                       starting address of receive buffer (choice)
           count
                                       number of elements in input buffer (non-negative in-
                                       teger)
 IN
           datatype
                                       data type of elements of input buffer (handle)
 IN
                                       operation (handle)
           op
 IN
           comm
                                       intracommunicator (handle)
 OUT
                                       communication request (handle)
           request
int MPI_Iexscan(void *sendbuf, void *recvbuf, int count,
              MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
              MPI_Request *request)
MPI_IEXSCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
MPI::Request MPI::Intracomm::Iexscan(const void* sendbuf, void* recvbuf,
               int count, const MPI::Datatype& datatype, const MPI::Op& op)
               const
```

MPI\_IEXSCAN is the nonblocking variant of MPI\_EXSCAN. It starts a nonblocking exclusive scan operation which delivers the same results as MPI\_EXSCAN after completion.

# 5.13 Correctness

A correct, portable program must invoke collective communications so that deadlock will not occur, whether collective communications are synchronizing or not. The following examples illustrate dangerous use of collective routines on intracommunicators.

#### **Example 5.24** The following is erroneous.

```
switch(rank) {
    case 0:
        MPI_Bcast(buf1, count, type, 0, comm);
        MPI_Bcast(buf2, count, type, 1, comm);
        break;
    case 1:
        MPI_Bcast(buf2, count, type, 1, comm);
        MPI_Bcast(buf1, count, type, 0, comm);
        break;
}
```

We assume that the group of comm is  $\{0,1\}$ . Two processes execute two broadcast operations in reverse order. If the operation is synchronizing then a deadlock will occur.

Collective operations must be executed in the same order at all members of the communication group.

# **Example 5.25** The following is erroneous.

```
3
     switch(rank) {
4
         case 0:
             MPI_Bcast(buf1, count, type, 0, comm0);
5
6
             MPI_Bcast(buf2, count, type, 2, comm2);
             break;
         case 1:
             MPI_Bcast(buf1, count, type, 1, comm1);
9
             MPI_Bcast(buf2, count, type, 0, comm0);
10
             break;
11
         case 2:
12
             MPI_Bcast(buf1, count, type, 2, comm2);
13
             MPI_Bcast(buf2, count, type, 1, comm1);
             break;
15
16
     }
```

Assume that the group of comm0 is  $\{0,1\}$ , of comm1 is  $\{1,2\}$  and of comm2 is  $\{2,0\}$ . If the broadcast is a synchronizing operation, then there is a cyclic dependency: the broadcast in comm2 completes only after the broadcast in comm0; the broadcast in comm0 completes only after the broadcast in comm1; and the broadcast in comm1 completes only after the broadcast in comm2. Thus, the code will deadlock.

Collective operations must be executed in an order so that no cyclic dependences occur.

# **Example 5.26** The following is erroneous.

```
switch(rank) {
    case 0:
        MPI_Bcast(buf1, count, type, 0, comm);
        MPI_Send(buf2, count, type, 1, tag, comm);
        break;
    case 1:
        MPI_Recv(buf2, count, type, 0, tag, comm, status);
        MPI_Bcast(buf1, count, type, 0, comm);
        break;
}
```

Process zero executes a broadcast, followed by a blocking send operation. Process one first executes a blocking receive that matches the send, followed by broadcast call that matches the broadcast of process zero. This program may deadlock. The broadcast call on process zero may block until process one executes the matching broadcast call, so that the send is not executed. Process one will definitely block on the receive and so, in this case, never executes the broadcast.

The relative order of execution of collective operations and point-to-point operations should be such, so that even if the collective operations and the point-to-point operations are synchronizing, no deadlock will occur.

#### Example 5.27 An unsafe, non-deterministic program.

```
switch(rank) {
    case 0:
        MPI_Bcast(buf1, count, type, 0, comm);
        MPI_Send(buf2, count, type, 1, tag, comm);
        break;
case 1:
        MPI_Recv(buf2, count, type, MPI_ANY_SOURCE, tag, comm, status);
        MPI_Bcast(buf1, count, type, 0, comm);
        MPI_Recv(buf2, count, type, MPI_ANY_SOURCE, tag, comm, status);
        break;
case 2:
        MPI_Send(buf2, count, type, 1, tag, comm);
        MPI_Bcast(buf1, count, type, 0, comm);
        break;
}
```

All three processes participate in a broadcast. Process 0 sends a message to process 1 after the broadcast, and process 2 sends a message to process 1 before the broadcast. Process 1 receives before and after the broadcast, with a wildcard source argument.

Two possible executions of this program, with different matchings of sends and receives, are illustrated in Figure 5.12. Note that the second execution has the peculiar effect that a send executed after the broadcast is received at another node before the broadcast. This example illustrates the fact that one should not rely on collective communication functions to have particular synchronization effects. A program that works correctly only when the first execution occurs (only when broadcast is synchronizing) is erroneous.

Finally, in multithreaded implementations, one can have more than one, concurrently executing, collective communication call at a process. In these situations, it is the user's responsibility to ensure that the same communicator is not used concurrently by two different collective communication calls at the same process.

Advice to implementors. Assume that broadcast is implemented using point-to-point MPI communication. Suppose the following two rules are followed.

- 1. All receives specify their source explicitly (no wildcards).
- 2. Each process sends all messages that pertain to one collective call before sending any message that pertain to a subsequent collective call.

Then, messages belonging to successive broadcasts cannot be confused, as the order of point-to-point messages is preserved.

It is the implementor's responsibility to ensure that point-to-point messages are not confused with collective messages. One way to accomplish this is, whenever a communicator is created, to also create a "hidden communicator" for collective communication. One could achieve a similar effect more cheaply, for example, by using a hidden tag or context bit to indicate whether the communicator is used for point-to-point or collective communication. (*End of advice to implementors*.)

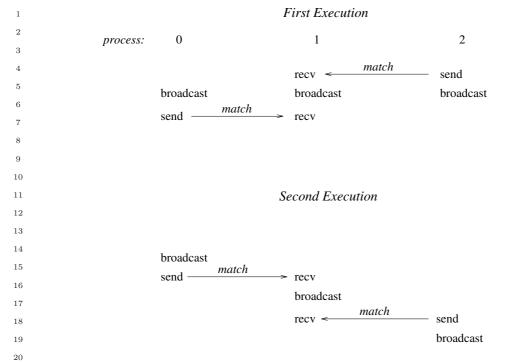


Figure 5.12: A race condition causes non-deterministic matching of sends and receives. One cannot rely on synchronization from a broadcast to make the program deterministic.

**Example 5.28** Blocking and nonblocking collective operations can be mixed, i.e., a blocking collective operation can be posted even if there is a nonblocking collective operation outstanding.

```
MPI_Request req;

MPI_Ibarrier(comm, &req);

MPI_Bcast(buf1, count, type, 0, comm);

MPI_Wait(&req, MPI_STATUS_IGNORE);
```

Each process starts a nonblocking barrier operation, participates in a blocking broadcast and then waits after every other process started the barrier operation. This effectively turns the broadcast into a synchronizing broadcast with possible communication/communication overlap (MPI\_Bcast is allowed, but not required to synchronize).

**Example 5.29** The starting order of collective operations on a particular communicator defines their matching. The following example shows an erroneous matching of different collective operations on the same communicator.

```
MPI_Request req;
switch(rank) {
   case 0:
     /* erroneous matching */
     MPI_Ibarrier(comm, &req);
     MPI_Bcast(buf1, count, type, 0, comm);
     MPI_Wait(&req, MPI_STATUS_IGNORE);
```

5.13. CORRECTNESS

```
break;
case 1:
    /* erroneous matching */
    MPI_Bcast(buf1, count, type, 0, comm);
    MPI_Ibarrier(comm, &req);
    MPI_Wait(&req, MPI_STATUS_IGNORE);
    break;
}
```

This ordering would match MPI\_lbarrier on rank 0 with MPI\_Bcast on rank 1 which is erroneous and the program behavior is undefined. However, if such an order is required, the user must create different duplicate communicators and perform the operations on them. The following program would be legal:

```
MPI_Request req;
MPI_Comm dupcomm;
MPI_Comm_dup(comm, &dupcomm);
switch(rank) {
    case 0:
        MPI_Ibarrier(comm, &req);
        MPI_Bcast(buf1, count, type, 0, dupcomm);
        MPI_Wait(&req, MPI_STATUS_IGNORE);
        break;
    case 1:
        MPI_Bcast(buf1, count, type, 0, dupcomm);
        MPI_Bcast(buf1, count, type, 0, dupcomm);
        MPI_Ibarrier(comm, &req);
        MPI_Wait(&req, MPI_STATUS_IGNORE);
        break;
}
```

Advice to users. The use of different communicators offers some flexibility regarding the matching of nonblocking collective operations. In this sense, communicators could be used as an equivalent to tags. However, communicator construction might induce huge overheads so that this should only be done if absolutely necessary. (End of advice to users.)

**Example 5.30** Nonblocking collective operations can rely on the same progression rules as nonblocking point-to-point messages. Thus, the following program is a valid MPI program and is guaranteed to terminate:

```
1
            MPI_Ibarrier(comm, &req);
2
            MPI_Recv(buf, count, dtype, 0, tag, comm, MPI_STATUS_IGNORE);
3
            MPI_Wait(&req, MPI_STATUS_IGNORE);
4
            break;
5
     }
6
         The MPI library must progress and finish the barrier in the MPI_Recv call which
     eventually completes the barrier operation on both processes and enables the matching
     MPI_Send.
9
10
     Example 5.31 Collective and point-to-point requests can be mixed in functions that en-
11
     able multiple completions. The following program is valid.
12
13
     MPI_Request reqs[2];
14
     switch(rank) {
15
16
          case 0:
            MPI_Ibarrier(comm, &reqs[0]);
17
            MPI_Send(buf, count, dtype, 1, tag, comm);
18
19
            MPI_Wait(&reqs[0], MPI_STATUS_IGNORE);
            break;
21
          case 1:
            MPI_Irecv(buf, count, dtype, 0, tag, comm, &reqs[0]);
22
            MPI_Ibarrier(comm, &reqs[1]);
23
            MPI_Waitall(2, reqs, MPI_STATUSES_IGNORE);
24
25
            break;
     }
26
27
         The Waitall call returns only after the barrier and the receive completed.
28
29
     Example 5.32 Multiple nonblocking collective operations can be outstanding on a single
30
     communicator and match in order.
31
     MPI_Request reqs[3];
32
33
     compute(buf1);
34
     MPI_Ibcast(buf1, count, type, 0, comm, &regs[0]);
35
     compute(buf2);
36
     MPI_Ibcast(buf2, count, type, 0, comm, &reqs[1]);
37
     compute(buf3);
38
     MPI_Ibcast(buf3, count, type, 0, comm, &reqs[2]);
39
     MPI_Waitall(3, regs, MPI_STATUSES_IGNORE);
40
41
           Advice to users. Pipelining and double-buffering techniques can efficiently be used
42
          to overlap computation and communication. (End of advice to users.)
           Advice to implementors. The use of pipelining can potentially generate a huge num-
45
          ber of outstanding requests. Thus, the number of outstanding requests should only
46
          be limited by physical memory. A hardware-supported implementation with limited
47
          resources should be able to fall back to a software implementation if its resources are
```

exhausted. (End of advice to implementors.)

**Example 5.33** Nonblocking collective operations can also be used to enable simultaneous collective operations on multiple overlapping communicators. The following example is started with three processes and three communicators. The first communicator comm1 includes ranks 0 and 1, comm2 includes ranks 1 and 2 and comm3 spans ranks 0 and 2. It is not possible to perform a blocking collective operation on all communicators because there exists no deadlock-free order to invoke them. However, nonblocking collective operations can easily be used to achieve this task.

```
MPI_Request reqs[2];
switch(rank) {
    case 0:
      MPI_Iallreduce(sbuf1, rbuf1, count, dtype, MPI_SUM, comm1, &reqs[0]);
      MPI_Iallreduce(sbuf3, rbuf3, count, dtype, MPI_SUM, comm3, &reqs[1]);
      break;
    case 1:
      MPI_Iallreduce(sbuf1, rbuf1, count, dtype, MPI_SUM, comm1, &reqs[0]);
      MPI_Iallreduce(sbuf2, rbuf2, count, dtype, MPI_SUM, comm2, &reqs[1]);
      break;
    case 2:
      MPI_Iallreduce(sbuf2, rbuf2, count, dtype, MPI_SUM, comm2, &reqs[0]);
      MPI_Iallreduce(sbuf3, rbuf3, count, dtype, MPI_SUM, comm3, &reqs[1]);
      break;
}
MPI_Waitall(2, reqs, MPI_STATUSES_IGNORE);
```

Advice to users. This method can be very useful if overlapping neighboring regions (halo or ghost zones) are used in collective operations. (End of advice to users.)

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